

**COMPARISON THEOREMS AND NECESSARY/SUFFICIENT CONDITIONS  
FOR EXISTENCE OF NONOSCILLATORY SOLUTIONS  
OF FORCED IMPULSIVE DELAY DIFFERENTIAL EQUATIONS**

**ТЕОРЕМИ ПОРІВНЯННЯ ТА НЕОБХІДНІ/ДОСТАТНІ УМОВИ ІСНУВАННЯ  
НЕОСЦИЛЯЦІЙНИХ РОЗВ'ЯЗКІВ ЗБУРЕНИХ ІМПУЛЬСНИХ  
ДИФЕРЕНЦІАЛЬНИХ РІВНЯНЬ ІЗ ЗАПІЗНЕННЯМ**

In 1997, A. H. Nasr provided necessary and sufficient conditions for the oscillation of the equation

$$x''(t) + p(t) |x(g(t))|^\eta \operatorname{sgn}(x(g(t))) = e(t),$$

where  $\eta > 0$ ,  $p$ , and  $g$  are continuous functions on  $[0, \infty)$  such that  $p(t) \geq 0$ ,  $g(t) \leq t$ ,  $g'(t) \geq \alpha > 0$ , and  $\lim_{t \rightarrow \infty} g(t) = \infty$ . It is important to note that the condition  $g'(t) \geq \alpha > 0$  is required. In this paper, we remove this restriction under the superlinear assumption  $\eta > 1$ . Infact, we can do even better by considering impulsive differential equations with delay and obtain necessary and sufficient conditions for the existence of nonoscillatory solutions and also a comparison theorem that enables us to apply known oscillation results for impulsive equations without forcing terms to yield oscillation criteria for our equations.

У 1997 році, А. Х. Наср отримав необхідні та достатні осциляційні умови для рівняння

$$x''(t) + p(t) |x(g(t))|^\eta \operatorname{sgn}(x(g(t))) = e(t),$$

де  $\eta > 0$ ,  $p$  та  $g$  – неперервні функції на  $[0, \infty)$  такі, що  $p(t) \geq 0$ ,  $g(t) \leq t$ ,  $g'(t) \geq \alpha > 0$  та  $\lim_{t \rightarrow \infty} g(t) = \infty$ . Слід зауважити, що необхідною тут є умова  $g'(t) \geq \alpha > 0$ . У даній статті ми усуваємо це обмеження при суперлінійному припущенні  $\eta > 1$ . Насправді, можна отримати навіть кращий результат, розглядаючи імпульсні диференціальні рівняння з запізненням, і встановити необхідні та достатні умови існування неосциляційних розв'язків, а також теорему порівняння, яка дає змогу застосувати відомі осциляційні результати для імпульсних рівнянь без збурюючих членів, щоб отримати осциляційні критерії для наших рівнянь.

**1. Introduction.** In 1997, A. H. Nasr in [1] provided necessary and sufficient conditions for the oscillation of the equation

$$x''(t) + p(t) |x(g(t))|^\eta \operatorname{sgn}(x(g(t))) = e(t), \quad (1)$$

where  $\eta > 0$ ,  $p$  and  $g$  are continuous functions on  $[0, \infty)$  such that  $p(t) \geq 0$ ,  $g(t) \leq t$ ,  $g'(t) \geq \alpha > 0$  and  $\lim_{t \rightarrow \infty} g(t) = \infty$ . Under a nice assumption on the function  $e$  (that the solution  $z$  of (5) is oscillatory and (22) holds), it is stated in reference [1] that the following conclusions hold: for  $\eta > 1$ , equation (1) is oscillatory if, and only if,  $\int_0^\infty t p(t) dt = \infty$ ; and for  $0 < \eta < 1$ , equation (1) is oscillatory if, and only if  $\int_0^\infty t^r p(t) dt = \infty$ . These conclusions extend those in [2] in which the well known Emden – Fowler equation without delay is studied.

It is important to note that the condition “ $g'(t) \geq \alpha > 0$ ” is needed in [1]. However, in [3], the author removes the restriction for the sublinear case  $0 < \eta < 1$ . In this paper, we intend to improve the same restriction for the superlinear case  $\eta > 1$  (see Corollary 3, or Theorems 1 and 4 below).

Indeed, we can do even better by considering impulsive differential equations with delay. More specifically, we obtain necessary and sufficient conditions for the existence of nonoscillatory solutions

and also a comparison theorem which enables us to apply known oscillation results (see, e.g., [4]) for impulsive equations without forcing terms to yield oscillation criteria for our equations (an example is illustrated in the last section).

To this end, we first recall some usual notations.  $\mathbf{R}$  and  $\mathbf{N}$  denote the set of real numbers and positive integers respectively.  $\mathbf{R}^+$  denotes the interval  $(0, +\infty)$ . Assume  $I_1$  and  $I_2$  are any two intervals in  $\mathbf{R}$ , we define

$$ALC(I_1, I_2) = \left\{ \varphi: I_1 \rightarrow I_2: \varphi \text{ is continuous almost everywhere (a.e.) in } I_1 \right. \\ \left. \text{with discontinuities of first kind} \right\},$$

$$PC(I_1, I_2) = \left\{ \varphi \in ALC(I_1, I_2): \varphi \text{ is continuous in each interval } I_1 \cap (t_k, t_{k+1}], k \in \mathbf{N}_0 \right\},$$

and

$$PC'(I_1, I_2) = \left\{ \varphi \in PC(I_1, I_2): \varphi \text{ is continuously differentiable a.e. in } I_1 \right\}.$$

We let

$$\Upsilon = \{t_1, t_2, \dots\}$$

be a set of real numbers such that  $0 = t_0 < t_1 < t_2 < \dots$  and  $\lim_{k \rightarrow \infty} t_k = +\infty$ . Also,  $x'(t)$  will be used to denote the left derivative of the function  $x(t)$  at  $t$ . We investigate the following nonlinear delay differential systems 'with impulsive effects'

$$(r(t)x'(t))' + F(t, x(g(t))) = e(t), \quad t \in [0, \infty) \setminus \Upsilon, \quad (2)$$

$$x(t_k^+) = a_k x(t_k), \quad k \in \mathbf{N}, \quad (3)$$

$$x'(t_k^+) = b_k x'(t_k), \quad k \in \mathbf{N}, \quad (4)$$

under some of the following conditions:

(A1) For  $t \geq 0$ , the function  $F(t, \mu)$  is continuous on  $\mathbf{R}$  with  $\mu F(t, \mu) \geq 0$  for  $\mu \neq 0$ , and for  $\mu \in \mathbf{R}$ , the function  $F(t, \mu)$  belongs to  $ALC([0, \infty), \mathbf{R})$ . Furthermore,  $F(t, \mu_2) \geq F(t, \mu_1)$  for  $t \geq 0$  and  $\mu_2 \geq \mu_1$ ;

(A2)  $g$  is a continuous function on  $[0, \infty)$  with  $g(t) \leq t$  for  $t \geq 0$  and  $\lim_{t \rightarrow \infty} g(t) = +\infty$ ;

(A3)  $0 < t_1 < t_2 < \dots$  are fixed numbers with  $\lim_{k \rightarrow \infty} t_k = +\infty$ ;

(A4) for each  $k \in \mathbf{N}$ ,  $a_k > 0$  and  $b_k > 0$ ;

(A5)  $r$  is a positive and differentiable function on  $[0, \infty)$ ;

(A6)  $e$  is a function on  $[0, \infty)$  continuous a.e.;

(A7) there are  $M > 0$  and  $m > 0$  such that  $m \leq A(s, t) \leq M$  for  $t \geq s \geq 0$  where

$$A(s, t) = \begin{cases} \prod_{s \leq t_k < t} a_k & \text{if } [s, t) \cap \Upsilon \neq \emptyset, \\ 1 & \text{if } [s, t) \cap \Upsilon = \emptyset. \end{cases}$$

Let  $\sigma \geq 0$  be given. We define  $r_\sigma = \min_{t \geq \sigma} g(t)$  and

$$B(s, t) = \begin{cases} \prod_{s \leq t_k < t} b_k & \text{if } [s, t) \cap \Upsilon \neq \emptyset, \\ 1 & \text{if } [s, t) \cap \Upsilon = \emptyset \end{cases}$$

for  $t \geq s \geq 0$ .

**Definition 1.** Let  $\sigma \geq 0$ . For any  $\phi \in PC'([r_\sigma, \sigma], \mathbf{R})$ , a function  $x \in PC'([r_\sigma, \infty), \mathbf{R})$  is said to be a solution of system (2)–(4) on  $[\sigma, \infty)$  satisfying the initial value condition

$$x(t) = \phi(t), \quad t \in [r_\sigma, \sigma],$$

if the following conditions are satisfied:

- (i)  $x' \in PC'([\sigma, \infty), \mathbf{R})$ ;
- (ii)  $x$  satisfies (2) for a.e.  $t \geq \sigma$ ;
- (iii)  $x$  satisfies (3) and (4) for  $t \geq \sigma$ .

**Definition 2.** Let  $x = x(t)$  be a real function defined for all sufficiently large  $t$ . We say that  $x$  is eventually positive (or negative) if there exists a number  $T$  such that  $x(t) > 0$  (respectively  $x(t) < 0$ ) for every  $t \geq T$ . We say that  $x$  is nonoscillatory if  $x(t)$  is eventually positive or eventually negative. Otherwise,  $x$  is said to be oscillatory.

In the subsequent discussions, we assume that there exists a solution  $z$  of the system

$$\begin{aligned} (r(t)z'(t))' &= e(t), \quad t \in [0, \infty) \setminus \Upsilon, \\ z(t_k^+) &= a_k z(t_k), \quad k \in \mathbf{N}, \\ z'(t_k^+) &= b_k z'(t_k), \quad k \in \mathbf{N}, \end{aligned} \tag{5}$$

on  $[\tau, \infty)$  for some  $\tau \geq 0$ . Let  $T \geq 0$  and  $\varphi \in PC([r_T, T], \mathbf{R})$ . For  $\delta \in PC([T, \infty), \mathbf{R})$ , we define a function  $w_\varphi(\delta)$  by

$$w_\varphi(\delta)(t) = \begin{cases} \delta(g(t)) & \text{if } g(t) > T, \\ \varphi(g(t)) & \text{if } r_T \leq g(t) \leq T \end{cases}$$

for  $t \geq T$ .

This paper is mainly concerned with oscillation of impulsive differential equations, but for more general background material, the reader is referred to [5–8].

**2. Main results.** We begin with a simple comparison principle.

**Lemma 1.** Assume that (A1)–(A6) hold, that the solution  $z$  of (5) is oscillatory, and

$$\int_{t_0}^{\infty} \frac{B(t_0, s)}{A(t_0, s)r(s)} ds = \infty \tag{6}$$

for any  $t_0 \geq 0$ . Let  $x$  be an eventually positive solution of system (2)–(4). Then  $x(t) > z(t)$  and  $x'(t) \geq z'(t)$  eventually.

**Proof.** Without loss of generality, we may assume that  $\tau = 0$ , and  $x(t) > 0$  for  $t \geq r_0$ . Let  $y(t) = x(t) - z(t)$  for  $t \geq 0$ . So the function  $y$  satisfies

$$(r(t)y'(t))' + F(t, x(g(t))) = 0, \quad \text{a.e. } t \geq 0, \quad (7)$$

and

$$y(t_k^+) = a_k y(t_k) \quad \text{and} \quad y'(t_k^+) = b_k y'(t_k), \quad k \in \mathbf{N}. \quad (8)$$

By (7), we see that  $(r(t)y'(t))' \leq 0$  for a.e.  $t \geq 0$ . Assume that there exists  $T > 0$  such that  $(r(T)y'(T))'$  exists and  $y'(T) < 0$ . By (8),

$$r(t)y'(t) \leq B(T, t)r(T)y'(T) < 0, \quad \text{a.e. } t \geq T. \quad (9)$$

Dividing (9) by  $r(t)A(T, t)$ , and then integrating the subsequent inequalities from  $T$  to  $t$ , we obtain

$$y(t) \leq A(T, t) \left( y(T) + r(T)'y'(T) \int_T^t \frac{B(T, s)}{A(T, s)r(s)} ds \right), \quad t \geq T.$$

In view of (6),  $y(t) < 0$  eventually. This is a contradiction since  $x(t) > 0$  eventually. So  $y'(t) \geq 0$  eventually. We note that it is impossible that  $y(t) \leq 0$  eventually because of  $x(t) > 0$  eventually. So there exists sufficiently large  $T_2$  such that  $y(T_2) > 0$ , then

$$y(t) \geq A(T_2, t)y(T_2) > 0, \quad t \geq T_2,$$

which implies that  $y(t) > 0$  eventually.

Lemma 1 is proved.

**Remark 1.** If  $e(t) = 0$  eventually, we may assume without loss of generality that the function  $z$  is the trivial function. By Lemma 1, we may see that the derivative of any eventually positive solution of system (2)–(4) is eventually nonnegative.

**Theorem 1.** Assume that (A1)–(A7) hold, that the solution  $z$  of (5) is bounded, and that

$$\int_{\varepsilon}^{\infty} \frac{1}{r(s)} \int_s^{\infty} \frac{F(v, c)}{B(s, v)} dv ds < \infty \quad (10)$$

for any  $c > 0$  and some  $\varepsilon \geq 0$ . Then system (2)–(4) has an eventually positive solution  $x$  which is bounded.

**Proof.** Without loss of generality, we may assume that  $|z(t)| \leq M$  for  $t > \tau$ . Let

$$d = M \left( \frac{M+1}{m} + 2 \right).$$

Clearly,  $d > 1$ . By (10), there exists  $T \in \Upsilon$  such that  $T > \max\{\tau, \varepsilon\}$  and

$$\int_T^{\infty} \frac{1}{r(s)} \int_s^{\infty} \frac{F(v, d)}{B(s, v)} dv ds \leq 1. \quad (11)$$

Let

$$X_1 = \{\delta \in PC([T, \infty), \mathbf{R}) : 1 \leq \delta(t) \leq d \text{ for } t \geq T\}. \quad (12)$$

Let  $\varphi(t) = 1$  for  $r_T \leq t \leq T$ . We define the operator  $H_1$  on  $X_1$  by

$$H_1(\delta)(t) = A(T, t) \frac{M+1}{m} + z(t) + \int_T^t \frac{A(s, t)}{r(s)} \int_s^\infty \frac{F(v, w_\varphi(\delta)(v))}{B(s, v)} dv ds \quad (13)$$

for  $t \geq T$ . Obviously,  $H_1(\delta) \in PC([T, \infty), \mathbf{R})$ . By the definition of  $w_\varphi(\delta)$ , we may see that  $1 \leq w(\delta)(t) \leq d$  for  $t \geq T$ . By (11),

$$H_1(\delta)(t) \geq m \frac{M+1}{m} - M = 1$$

and

$$H_1(\delta)(t) \leq M \frac{M+1}{m} + M + M \int_T^t \frac{1}{r(s)} \int_s^\infty \frac{F(v, d)}{B(s, v)} dv ds \leq M \left( \frac{M+1}{m} + 2 \right) = d \quad (14)$$

for  $t \geq T$ . So  $H_1(X_1) \subseteq X_1$ . We shall use the Knaster–Tarski fixed point theorem to prove that  $H_1$  has a fixed point in  $X_1$ . We first define a relation in  $X_1$ . If  $\delta_1$  and  $\delta_2$  belong to  $X_1$ , let us say that  $\delta_1 \leq \delta_2$  if and only if  $\delta_1(t) \leq \delta_2(t)$  a.e. on  $[T, \infty)$ . Clearly,  $X_1$  is a complete lattice. Given  $\delta_1, \delta_2 \in X_1$  with  $\delta_1 \leq \delta_2$ . Then  $w_\varphi(\delta_1)(t) \leq w_\varphi(\delta_2)(t)$  for a.e.  $t \geq T$ , which follows that  $F(t, w_\varphi(\delta_1)(t)) \leq F(t, w_\varphi(\delta_2)(t))$  for a.e.  $t \geq T$ . Then  $H_1(\delta_1)(t) \leq H_1(\delta_2)(t)$  for a.e.  $t \geq T$ . So  $H_1$  is increasing in  $X_1$ . By the Knaster–Tarski fixed point theorem, there exists  $\theta_1 \in X_1$  such that  $H_1(\theta_1) = \theta_1$ . Let

$$x(t) = \begin{cases} \theta_1(t) & \text{if } t > T, \\ 1 & \text{if } T \geq t \geq r_T. \end{cases}$$

Clearly,  $x \in PC'([T, \infty), [1, d])$ . Let  $T_1 > 0$  such that  $r_{T_1} > T$ . We note that  $x(g(t)) = w_\varphi(\theta_1)(t)$  for  $t \geq T_1$ . In view of  $H_1(\theta_1) = \theta_1$ , we have

$$x'(t) = z'(t) + \frac{B(T_1, t)}{r(t)} \int_t^\infty \frac{F(s, x(g(s)))}{B(T_1, s)} ds, \quad t \geq T_1, \quad (15)$$

which leads us to  $x' \in PC'([T_1, \infty), \mathbf{R})$  and

$$(r(t)x'(t))' + F(t, x(g(t))) = e(t), \quad \text{a.e. } t > T_1.$$

For any  $t_k \geq T_1$ , by  $H_1(\theta_1) = \theta_1$  and (15),

$$x(t_k^+) = a_k x(t_k) \quad \text{and} \quad x'(t_k^+) = b_k x'(t_k).$$

Then  $x$  is a bounded and positive solution of system (2)–(4) on  $[T_1, \infty)$ .

Theorem 1 is proved.

As a direct consequence, we have the following dual conclusion.

**Corollary 1.** Assume that (A1)–(A7) hold, that the solution  $z$  of (5) is bounded, and that

$$\int_{\varepsilon}^{\infty} \frac{1}{r(s)} \int_s^{\infty} \frac{F(v, \tau)}{B(s, v)} dv ds > -\infty \quad (16)$$

for any  $\tau < 0$  and some  $\varepsilon \geq 0$ . Then system (2)–(4) has an eventually negative solution  $x$  which is bounded.

**Lemma 2.** Assume that (A1)–(A6) hold. If the system

$$\begin{aligned} (r(t)u'(t))' + F(t, u(g(t))) &\leq 0, \quad t \in [0, \infty) \setminus \Upsilon, \\ u(t_k^+) &= a_k u(t_k), \quad k \in \mathbf{N}, \\ u'(t_k^+) &= b_k u'(t_k), \quad k \in \mathbf{N}, \end{aligned} \quad (17)$$

has an eventually positive solution  $u$  with  $u(t)u'(t) \geq 0$  eventually, then

$$(r(t)u'(t))' + F(t, u(g(t))) = 0, \quad t \in [0, \infty) \setminus \Upsilon, \quad (18)$$

$$u(t_k^+) = a_k u(t_k), \quad k \in \mathbf{N}, \quad (19)$$

$$u'(t_k^+) = b_k u'(t_k), \quad k \in \mathbf{N}, \quad (20)$$

has an eventually positive solution  $\tilde{u}$  with  $\tilde{u}(t)\tilde{u}'(t) \geq 0$  eventually.

**Proof.** There is  $T > 0$  such that  $u(t) > 0$  and  $u'(t) \geq 0$  for  $t \geq r_T$ . For any  $d \geq t \geq T$ , we divide (17) by  $B(T, t)$ , and then integrate from  $t$  to  $d$ . We have

$$\frac{r(d)u'(d)}{B(T, d)} - \frac{r(t)u'(t)}{B(T, t)} + \int_t^d \frac{F(s, u(g(s)))}{B(T, s)} ds \leq 0.$$

Since  $u'(d) \geq 0$  and  $d$  is arbitrary, we may see that

$$u'(t) \geq \frac{1}{r(t)} \int_t^{\infty} \frac{F(s, u(g(s)))}{B(t, s)} ds$$

for  $t \geq T$ . Again, we divide the above inequality by  $A(T, t)$  and then integrate from  $T$  to  $t$ . Then we have

$$u(t) \geq A(T, t) \left( u(T) + \int_T^t \frac{1}{A(T, s)r(s)} \int_s^{\infty} \frac{F(v, u(g(v)))}{B(s, v)} dv ds \right) \quad (21)$$

for  $t \geq T$ . Let

$$X_2 = \{ \delta \in PC([T, \infty), \mathbf{R}) : A(T, t)u(T) \leq \delta(t) \leq u(t) \text{ for } t \geq T \}$$

and we define an operator  $H_2$  on  $X_2$  by

$$H_2(\delta)(t) = A(T, t) \left( u(T) + \int_T^t \frac{1}{A(T, s)r(s)} \int_s^\infty \frac{F(v, w_u(\delta)(v))}{B(s, v)} dv ds \right)$$

for  $t \geq T$ . Clearly,  $X_2$  is nonempty because  $u \in X_2$ . We impose in  $X_2$  the same order relation imposed in the set  $X_1$ . Then  $X_2$  is a complete lattice. Given  $\delta_1, \delta_2 \in X_2$  with  $\delta_1 \leq \delta_2$ . We note that

$$0 < w_u(\delta_1)(t) \leq w_u(\delta_2)(t) \leq u(g(t))$$

for  $t \geq T$ . By assumption,

$$F(t, w_u(\delta_1)(t)) \leq F(t, w_u(\delta_2)(t)) \leq F(t, u(g(t))),$$

where  $t \geq T$ . By (21),

$$A(T, t)u(T) \leq H_2(\delta_1)(t) \leq H_2(\delta_2)(t) \leq u(t)$$

for  $t \geq T$ . So  $H_2(X_2) \subseteq X_2$  and  $H_2$  is increasing on  $X_2$ . By the Knaster–Tarski fixed point Theorem, there exists  $\theta_2 \in X_2$  such that  $H_2(\theta_2) = \theta_2$ . Let

$$\tilde{\mu}(t) = \begin{cases} \theta_2(t) & \text{if } t > T, \\ u(t) & \text{if } T \geq t \geq r_T. \end{cases}$$

Similar to the proof of Theorem 1, we may check that  $\tilde{\mu}$  is an eventually positive solution of system (18)–(20) with  $\tilde{\mu}(t)\tilde{\mu}'(t) \geq 0$  eventually.

Lemma 2 is proved.

We now compare forced impulsive equations and unforced impulsive equations.

**Theorem 2.** Assume that (A1)–(A6) and (6) hold and the solution  $z$  of (5) is oscillatory. Assume that there exist two sequences  $\{s_n\}_{n \in \mathbf{N}}$  and  $\{\tilde{s}_n\}_{n \in \mathbf{N}}$  such that

$$z(s_n) = \inf \left\{ \frac{z(t)}{A(s_n, t)} : t \geq s_n \right\} \quad \text{and} \quad z(\tilde{s}_n) = \sup \left\{ \frac{z(t)}{A(\tilde{s}_n, t)} : t \geq \tilde{s}_n \right\}. \quad (22)$$

If the system (2)–(4) has a nonoscillatory solution  $x$ , then the system

$$(r(t)u'(t))' + F(t, u(g(t))) = 0, \quad t \in [0, \infty) \setminus \Upsilon, \quad (23)$$

$$u(t_k^+) = a_k u(t_k), \quad k \in \mathbf{N}, \quad (24)$$

$$u'(t_k^+) = b_k u'(t_k), \quad k \in \mathbf{N}, \quad (25)$$

has a nonoscillatory solution  $u$  such that  $u(t)u'(t) \geq 0$  eventually. Furthermore,  $u(t)$  is bounded if  $x(t)$  is bounded and (A7) holds.

**Proof.** We first assume that  $x$  is an eventually positive solution of (2)–(4). By Lemma 1,  $x(t) > z(t)$  and  $x'(t) \geq z'(t)$  eventually. Without loss of generality, we may assume that  $\tau = 0$ ,  $x(t) > 0$ ,  $x(t) > z(t)$  and  $x'(t) \geq z'(t)$  for  $t \geq s_1$ . Let  $y(t) = x(t) - z(t)$  and  $v(t) = y(t) + A(s_1, t)z(s_1)$  for  $t \geq s_1$ . Clearly,  $v, v' \in PC'([s_1, \infty), \mathbf{R})$ . By Lemma 1, we see that  $y'(t) \geq 0$  for  $t \geq s_1$ . So  $y(t) \geq A(s_1, t)y(s_1)$  for  $t \geq s_1$ , from which it follows that

$$v(t) = y(t) + A(s_1, t)z(s_1) \geq A(s_1, t)(y(s_1) + z(s_1)) = A(s_1, t)x(s_1) > 0 \quad (26)$$

for  $t \geq s_1$ . We note that

$$v'(t) = y'(t) \geq 0, \quad (27)$$

and by (22)

$$x(t) = y(t) + z(t) \geq y(t) + A(s_1, t)z(s_1) = v(t) \quad (28)$$

for  $t \geq s_1$ . In view of (A3), there exists  $T > s_1$  such that  $r_T > s_1$ . By (28), then  $x(g(t)) \geq v(g(t)) > 0$  and

$$F(t, x(g(t))) \geq F(t, v(g(t)))$$

for  $t \geq T$ . By (27) and (28), we see that

$$(r(t)v'(t))' + F(t, v(g(t))) \leq (r(t)y'(t))' + F(t, x(g(t))) = 0, \quad \text{a.e. } t \geq T.$$

We observe that  $v(t_k^+) = a_k v(t_k)$  and  $v'(t_k^+) = b_k v'(t_k)$  for  $t_k \geq T$ . In view of (26), the function  $v$  is an eventually positive solution of system

$$\begin{aligned} (r(t)u'(t))' + F(t, u(g(t))) &\leq 0, \quad t \in [0, \infty) \setminus \Upsilon, \\ u(t_k^+) &= a_k u(t_k), \quad k \in \mathbf{N}, \\ u'(t_k^+) &= b_k u'(t_k), \quad k \in \mathbf{N}, \end{aligned} \quad (29)$$

such that  $v'(t) \geq 0$  for  $t \geq T$ . By Lemma 2, the system (23)–(25) has an eventually positive solution  $u$  such that  $v(t) \geq u(t)$  and  $u'(t) \geq 0$  eventually. Assume that  $x$  is bounded and (A7) holds. By (22), we note that the function  $z$  is bounded. Then the function  $v$  is bounded. So the function  $u$  is also bounded.

Lastly, we assume that  $x$  is an eventually negative solution of (2)–(4). Let  $G(t, x) = -F(t, -x)$  for  $x \in \mathbf{R}$ . Let  $\tilde{x}(t) = -x(t)$  and  $\tilde{z}(t) = -z(t)$  for sufficiently large  $t$ . Then  $\tilde{x}$  is an eventually positive solution

$$\begin{aligned} (r(t)x'(t))' + G(t, x(g(t))) &= -e(t), \quad t \in [0, \infty) \setminus \Upsilon, \\ x(t_k^+) &= a_k x(t_k), \quad k \in \mathbf{N}, \\ x'(t_k^+) &= b_k x'(t_k), \quad k \in \mathbf{N}. \end{aligned}$$

By (22), we note that

$$\tilde{z}(\tilde{s}_n) = -z(\tilde{s}_n) = -\sup \left\{ \frac{z(t)}{A(\tilde{s}_n, t)} : t \geq \tilde{s}_n \right\} = \inf \left\{ \frac{\tilde{z}(t)}{A(\tilde{s}_n, t)} : t \geq \tilde{s}_n \right\},$$

for  $n \in \mathbf{N}$ . By the former case, we see that the system

$$(r(t)u'(t))' + G(t, u(g(t))) = 0, \quad t \in [0, \infty) \setminus \Upsilon,$$



$$u(t_k^+) = a_k u(t_k), \quad k \in \mathbf{N},$$

$$u'(t_k^+) = b_k u'(t_k), \quad k \in \mathbf{N},$$

has an eventually positive solution  $\tilde{u}(t)$  such that  $\tilde{u}'(t) \geq 0$  eventually. Furthermore,  $\tilde{u}$  is bounded if  $\tilde{x}$  is bounded and (A7) holds. Let  $u(t) = -\tilde{u}(t)$  for sufficiently large  $t$ . So the system (23)–(25) has an eventually negative solution  $u$  such that  $u'(t) \leq 0$  eventually, and  $u$  is bounded if  $x$  is bounded and (A7) holds.

Theorem 2 is proved.

**Theorem 3.** Assume that (A1)–(A7) hold and the solution  $z$  of (5) satisfies  $\lim_{t \rightarrow \infty} z(t) = 0$ . If the system (23)–(25) has a nonoscillatory solution  $u$  with  $u(t)u'(t) \geq 0$  eventually, then the system (2)–(4) has a nonoscillatory solution  $x$ .

**Proof.** Assume that  $u$  is an eventually positive solution. Without loss of generality, we may assume that  $u(t) > 0$  and  $u'(t) \geq 0$  for  $t \geq r_0$ . Then

$$u(\bar{T}) \geq A(0, \bar{T})u(0) \geq mu(0) \quad \text{for any } \bar{T} \geq 0. \quad (30)$$

Since  $\lim_{t \rightarrow \infty} z(t) = 0$ , there exists  $T > 0$  such that  $|z(t)| < m^2 u(0)/3$  for  $t \geq T$ . By the same reasoning for obtaining the inequality (21), we have

$$u(t) \geq A(T, t) \left( u(T) + \int_T^t \frac{1}{r(s)} \int_s^\infty \frac{F(v, u(g(v)))}{B(s, v)} dv ds \right) \geq m^2 u(0) \quad (31)$$

for  $t \geq 0$ . Let

$$X_3 = \left\{ \delta \in PC([T, \infty), \mathbf{R}) : m^2 \frac{u(0)}{3} \leq \delta(t) \leq u(t) \text{ for } t \geq T \right\}.$$

Clearly,  $X_3$  is nonempty because  $u \in X_3$ . We impose in  $X_3$  the same order relation imposed in  $X_1$ . Then  $X_3$  is a complete lattice. We define an operator  $H_3$  on  $X_3$  by

$$H_3(\delta)(t) = A(T, t) \frac{2u(T)}{3} + z(t) + \int_T^t \frac{A(s, t)}{r(s)} \int_s^\infty \frac{F(v, w_u(\delta)(v))}{B(s, v)} dv ds$$

for  $t \geq T$ . In view of (30),

$$H_3(\delta)(t) \geq m \frac{2u(T)}{3} - |z(t)| \geq m^2 \frac{u(0)}{3}, \quad t \geq T,$$

for any  $\delta \in X_3$ . Given  $\delta_1, \delta_2 \in X_3$  with  $\delta_1 \leq \delta_2$ . We note that

$$0 \leq w_u(\delta_1)(t) \leq w_u(\delta_2)(t) \leq u(g(t))$$

for  $t \geq T$ . By assumption, (30) and (31), we have

$$\begin{aligned} & H_3(\delta_1)(t) \leq H_3(\delta_2)(t) \leq \\ & \leq A(T, t) \frac{2u(T)}{3} + |z(t)| + \int_T^t \frac{A(s, t)}{r(s)} \int_s^\infty \frac{F(v, u(g(v)))}{B(s, v)} dv ds \leq \end{aligned}$$

$$\begin{aligned} &\leq A(T, t) \frac{2u(T)}{3} + m^2 \frac{u(0)}{3} + \int_T^t \frac{A(s, t)}{r(s)} \int_s^\infty \frac{F(v, u(g(v)))}{B(s, v)} dv ds < \\ &< A(T, t) \frac{2u(T)}{3} + m \frac{u(T)}{3} + \int_T^t \frac{A(s, t)}{r(s)} \int_s^\infty \frac{F(v, u(g(v)))}{B(s, v)} dv ds \leq u(t) \end{aligned}$$

for  $t \geq T$ . So  $H_3(X_3) \subseteq X_3$  and  $H_3$  is increasing on  $X_3$ . By the Knaster–Tarski fixed point theorem, there exists  $\theta_3 \in X_3$  such that  $H_3(\theta_3) = \theta_3$ . Let

$$x(t) = \begin{cases} \theta_3(t), & t > T, \\ u(t), & T \geq t \geq r_T. \end{cases}$$

Let  $T_1 > 0$  such that  $r_{T_1} > T$ . We note that  $x(g(t)) = w_u(\theta_3)(t)$  for  $t \geq T_1$ . In view of  $H_3(\theta_3) = \theta_3$ , we have

$$x'(t) = z'(t) + \frac{B(T_2, t)}{r(t)} \int_t^\infty \frac{F(s, x(g(s)))}{B(T_2, s)} ds$$

from which it follows that  $x' \in PC'([T_1, \infty), \mathbf{R})$  and

$$(r(t)x'(t))' + F(t, x(g(t))) = e(t), \quad \text{a.e. } t \geq T_1.$$

For any  $t_k \geq T_2$ , by  $H_3(\theta_3) = \theta_3$  and (15),

$$x(t_k^+) = a_k x(t_k) \quad \text{and} \quad x'(t_k^+) = b_k x'(t_k).$$

Then  $x$  is a positive solution of system (2)–(4) on  $[T_1, \infty)$ .

Theorem 3 is proved.

We remark that in the proof of Theorem 3, we see that in the condition (A7), we only need “ $A(s, t) \geq m$  for  $t \geq s \geq 0$ ”.

The following result offers a *necessary and sufficient* oscillation theorem for (2)–(4).

**Corollary 2.** *Assume that (A1)–(A7) and (6) hold, and the solution  $z$  of (5) is oscillatory and  $\lim_{t \rightarrow \infty} z(t) = 0$ . Then the system (2)–(4) has a nonoscillatory solution  $x$  if, and only if, system (23)–(25) has a nonoscillatory solution  $u$ .*

**Proof.** We first show that there exist two sequences  $\{s_n\}_{n \in \mathbf{N}}$  and  $\{\tilde{s}_n\}_{n \in \mathbf{N}}$  such that (22) holds. Let  $\tilde{z}(t) = z(t)/A(\tau, t)$  for  $t \geq \tau$ . Clearly,  $\tilde{z}(t)$  is continuous on  $[\tau, \infty)$  and is oscillatory. By (A7) and  $\lim_{t \rightarrow \infty} z(t) = 0$ , we see that  $\lim_{t \rightarrow \infty} \tilde{z}(t) = 0$ . In view of oscillation, there exists  $s_1 > \tau$  such that  $\tilde{z}(s_1) \leq \tilde{z}(t)$  for  $t \geq s_1$ , which implies that

$$z(s_1) \leq \frac{z(t)}{A(s_1, t)} \quad \text{for } t \geq s_1.$$

There exists  $s_2 > s_1$  such that  $\tilde{z}(s_2) \leq \tilde{z}(t)$  for  $t \geq s_1$ , which implies that

$$z(s_2) \leq \frac{z(t)}{A(s_2, t)} \quad \text{for } t \geq s_2.$$

By induction, we can take sequence  $\{s_n\}_{n \in \mathbf{N}}$  such that (22) holds. Similarly, we can also take the sequence  $\{\tilde{s}_n\}_{n \in \mathbf{N}}$  such that (22) holds. By Theorem 2, the necessary condition holds. Conversely, assume that  $u$  is nonoscillatory solution of system (23)–(25). By Lemma 1, we see that  $u(t)u'(t) \geq 0$  eventually. By Theorem 3, the sufficient condition holds.

Corollary 2 is proved.

We have another *necessary and sufficient* condition for the existence of bounded nonoscillatory solutions of (2)–(4).

**Corollary 3.** *Assume that (A1)–(A7) and (6) hold and  $F(t, \mu) = p(t)f(\mu)$  where  $p \in ALC([0, \infty), [0, \infty))$  and  $f$  is nondecreasing on  $\mathbf{R}$  with  $\mu f(\mu) > 0$  for  $\mu \neq 0$ . Assume that the solution  $z$  of (5) is oscillatory, and there exist two sequences  $\{s_n\}_{n \in \mathbf{N}}$  and  $\{\tilde{s}_n\}_{n \in \mathbf{N}}$  such that (22) hold. Then the system (2)–(4) has a bounded and nonoscillatory solution if, and only if,*

$$\int_{\varepsilon}^{\infty} \frac{1}{r(s)} \int_s^{\infty} \frac{p(v)}{B(s, v)} dv ds < \infty \quad (32)$$

for some  $\varepsilon \geq 0$ .

**Proof.** Assume that (32) holds. Clearly, (10) and (16) holds. By (A7) and (22), we note that the function  $z$  is bounded. By Theorem 1 and Corollary 1, the necessary condition holds. Conversely, we see that by Theorem 2, the system (23)–(25) has a nonoscillatory solution  $u$  such that  $u(t)u'(t) \geq 0$  eventually, and  $u$  is bounded. Assume that  $u$  is eventually positive with  $u'(t) \geq 0$  eventually. Then there exists  $T > 0$  such that  $u(t) > 0$  and  $u'(t) \geq 0$  for  $t \geq T$ . We observe that

$$M_u \geq u(t) \geq A(T, t)u(T) \geq mu(T) > 0$$

for  $t \geq T$  and some  $M_u > 0$ . So the function  $u$  has a positive lower bound. Since  $f$  is nondecreasing on  $\mathbf{R}$ , there is  $m_f > 0$  such that  $f(u(t)) \geq m_f$  for  $t \geq T$ . We observe that

$$\left( \frac{r(t)u'(t)}{u(t)} \right)' = \left( \frac{r(t)u'(t)}{u(t)} \right)' \leq -\frac{p(t)f(u(g(t)))}{u(t)} \leq -\frac{m_f}{M_u} p(t)$$

for  $t \geq T$ . We divide the above inequality by  $B(T, t)/A(T, t)$  and then integrate from  $t$  to  $d$  where  $d \geq t \geq T$ . We have

$$\frac{A(T, d)r(d)u'(d)}{B(T, d)u(d)} - \frac{A(T, t)r(t)u'(t)}{B(T, t)u(t)} \leq -\frac{m_f}{M_u} \int_t^d \frac{A(T, s)p(s)}{B(T, s)} ds$$

for  $d \geq t \geq T$ . Since  $u'(d) > 0$  and  $d$  is arbitrary, we see that

$$\frac{u'(t)}{u(t)} \geq \frac{m_f}{M_u r(t)} \int_t^{\infty} \frac{A(t, s)p(s)}{B(t, s)} ds$$

for  $t \geq T$ , from which it follows that

$$u'(t) \geq u'(t) \frac{mu(T)}{u(t)} \geq \frac{m^2 u(T) m_f}{M_u} \frac{1}{r(t)} \int_t^{\infty} \frac{p(s)}{B(t, s)} ds.$$

We divide the above inequality by  $A(T, t)$ , and then integrate from  $T$  to  $t$ . Then

$$\begin{aligned} u(t) &\geq A(T, t)u(T) + \frac{m^2 u(T) m_f}{M_u} \int_T^t \frac{A(s, t)}{r(s)} \int_t^\infty \frac{p(s)}{B(t, s)} ds \geq \\ &\geq m \left( u(T) + \frac{m u(T) m_f}{M_u} \int_T^t \frac{1}{r(s)} \int_t^\infty \frac{p(s)}{B(t, s)} ds \right) \end{aligned} \quad (33)$$

for  $t \geq T$ . Since  $u$  is bounded, we may easily see that (32) holds. Assume that  $u$  is eventually negative with  $u'(t) \leq 0$  eventually. Then  $-u$  is an eventually positive solution of system

$$(r(t)u'(t))' + p(t)\tilde{f}(u(g(t))) = 0, \quad t \in [0, \infty) \setminus \Upsilon, \quad (34)$$

$$u(t_k^+) = a_k u(t_k), \quad k \in \mathbf{N}, \quad (35)$$

$$u'(t_k^+) = b_k u'(t_k), \quad k \in \mathbf{N}, \quad (36)$$

where  $\tilde{f}(\mu) = -f(-\mu)$  for  $\mu \in \mathbf{R}$ . Similarly, the function  $-u$  has a positive lower bound. We note that the function  $\tilde{f}$  satisfies all assumption of  $f$ . So the condition (32) holds.

Corollary 3 is proved.

**Theorem 4.** Assume that the hypotheses of Corollary 3 hold except for the condition (A7), and that  $g'(t) > 0$  for  $t \geq 0$ ,  $a_k \geq 1$  for  $k \in \mathbf{N}$ , and

$$\int_\varepsilon^\infty \frac{1}{f(\mu)} d\mu < \infty \quad \text{for any } \varepsilon > 0. \quad (37)$$

If the system (2)–(4) has a nonoscillatory solution, then (32) holds.

**Proof.** Since the system (2)–(4) has a nonoscillatory solution, by Theorem 2, we see that system (23)–(25) has a nonoscillatory solution  $u$  with  $u(t)u'(t) \geq 0$  eventually. Assume that  $u$  is eventually positive with  $u'(t) \geq 0$  eventually. There exists  $T > 0$  such that  $u(t) > 0$  and  $u'(t) \geq 0$  for  $t \geq t_T$ . For any  $T_1 > t \geq T$ , we integrate (23) from  $t$  to  $T_1$ , and we obtain

$$\frac{r(T_1)u'(T_1)}{B(T, T_1)} - \frac{r(t)u'(t)}{B(T, t)} + \int_t^{T_1} \frac{p(s)f(u(g(s)))}{B(T, s)} ds = 0. \quad (38)$$

Since  $T_1$  is arbitrary, by (38), we see that

$$\frac{r(t)u'(t)}{B(T, t)} \geq \int_t^\infty \frac{p(s)f(u(g(s)))}{B(T, s)} ds, \quad t \geq T. \quad (39)$$

Since  $g'(t) > 0$  for  $t \geq 0$  and  $a_k \geq 1$  for  $k \in \mathbf{N}$ , we may see that  $g(s) \geq g(t)$  and  $A(t, s) \geq 1$  for  $s \geq t \geq T$ , from which it follows that

$$u(g(s)) \geq A(g(t), g(s))u(g(t)) \geq u(g(t)) \quad (40)$$

for  $s \geq t \geq T$ . Since  $f$  is nondecreasing on  $\mathbf{R}$ , we may further see that

$$f(u(g(s))) \geq f(u(g(t))) > 0 \quad (41)$$

for  $s \geq t \geq T$ . We divided (39) by  $f(u(g(t)))$ . Then

$$\frac{u'(g(t))}{f(u(g(t)))} \geq \frac{1}{r(g(t))} \int_{g(t)}^{\infty} \frac{p(s)f(u(g(s)))}{B(g(t), s)f(u(g(t)))} ds,$$

from which it follows that, by (41),

$$\frac{u'(g(t))}{f(u(g(t)))} \geq \frac{1}{r(g(t))} \int_{g(t)}^{\infty} \frac{p(s)}{B(g(t), s)} ds \quad (42)$$

for  $t \geq T$ . We multiply (42) by  $g'(t)$ , and then integrate from  $T$  to  $\infty$ . We obtain

$$\int_T^{\infty} \frac{(u(g(s)))'}{f(u(g(s)))} ds \geq \int_T^{\infty} \frac{g'(s)}{r(g(s))} \left( \int_{g(s)}^{\infty} \frac{p(v)}{B(g(s), v)} dv \right) ds = \int_{g(T)}^{\infty} \frac{1}{r(s)} \left( \int_s^{\infty} \frac{p(v)}{B(s, v)} dv \right) ds. \quad (43)$$

By (37), (40) and (43), we see that

$$\int_{g(T)}^{\infty} \frac{1}{r(s)} \left( \int_s^{\infty} \frac{p(v)}{B(s, v)} dv \right) ds \leq \int_T^{\infty} \frac{(u(g(s)))'}{f(u(g(s)))} ds \leq \int_{u(g(T))}^{\infty} \frac{1}{f(\mu)} d\mu < \infty.$$

So (32) holds. Assume that  $u(t)$  is eventually negative. Let  $\tilde{f}(\mu) = -f(-\mu)$  for  $\mu \in \mathbf{R}$ . By (37), we have

$$\int_{\varepsilon}^{\infty} \frac{1}{\tilde{f}(\mu)} d\mu < \infty \quad \text{for any } \varepsilon > 0.$$

We note that  $-u(t)$  is eventually positive solution of system (34)–(36). Similarly, we may verify (32).

Theorem 4 is proved.

Recall now the equation (1) under the condition  $\eta > 1$ . For the ease of discussion, we state the result in [1].

**Corollary 4** [1]. *Let  $\eta > 1$  be given and let  $e$ ,  $p$  and  $g$  be continuous functions on  $[0, \infty)$  such that  $\lim_{t \rightarrow \infty} g(t) = \infty$ ,  $p(t) \geq 0$ ,  $g(t) \leq t$  and  $g'(t) \geq \alpha > 0$  for  $t \geq 0$ . Assume that there exists a bounded function  $z(t)$  on  $[0, \infty)$  such that  $z''(t) = e(t)$  for all sufficient large  $t$ , and that  $z$  is oscillatory and (22) holds. Then*

$$\int_0^{\infty} sp(s) ds < \infty \quad (44)$$

*if, and only if, the equation (1) has a nonoscillatory solution.*

Because the equation (1) has no impulsive effects,  $a_k = b_k = 1$  for all  $k$ . That is,  $A(s, t) = B(s, t) = 1$  for  $t \geq s \geq 0$ . Let  $r(t) = 1$  for  $t \geq 0$ . Clearly, (6) holds and

$$\int_0^{\infty} \frac{1}{r(s)} \int_s^{\infty} \frac{p(v)}{B(s, v)} dv ds = \int_0^{\infty} sp(s) ds.$$

So either condition (10) or (32) is equivalent to (44). We have the following conclusions.

(1) Assume that we replace the condition “ $g'(t) \geq \alpha > 0$  for  $t \geq 0$ ” by  $g'(t) > 0$  for  $t \geq 0$ . By Theorem 1 and 4, we can obtain the same Corollary in [1].

(2) Assume that we remove the condition “ $g'(t) \geq \alpha > 0$  for  $t \geq 0$ ”. By Corollary 3, we can see that (44) holds if, and only if, the equation (1) has a nonoscillatory and bounded solution. We note that if the equation (1) has a nonoscillatory and unbounded solution, the condition (44) may not be true. So this result is sharp without the condition “ $g'(t) > 0$  for  $t \geq 0$ .” We give an example to illustrate it. Let  $\varepsilon_1(t) = t^{1/3}(2 + \sin t)$  for  $t \geq 0$ . Clearly, there exists  $a > 0$  such that  $\varepsilon_1(t) \leq t$  for  $t \geq a$ . Let

$$g(t) = \begin{cases} \varepsilon_1(t), & t \geq a, \\ \varepsilon_2(t), & a > t \geq 0, \end{cases}$$

where  $\varepsilon_2$  is a nonnegative and continuous function on  $[0, a]$  with  $\varepsilon_2(t) \leq t$  for  $0 \leq t \leq a$ , and  $\varepsilon_1(a) = \varepsilon_2(a)$ . By simple computation, we can see that  $\lim_{t \rightarrow \infty} g(t) = \infty$  and  $g(t) \leq t$  for  $t \geq 0$ , and it is impossible that  $g'(t) > 0$  for sufficiently large  $t$ . We consider a special equation

$$x''(t) + \frac{1}{4t^{3/2}g(t)}x^2(g(t)) = 0, \quad t \geq 0. \quad (45)$$

Then the function  $x(t) = \sqrt{t}$  is an eventually positive solution of (45) and is unbounded. But we can see that

$$\int_a^{\infty} \frac{t}{4t^{3/2}g(t)} dt = \int_a^{\infty} \frac{1}{4t^{5/6}(2 + \sin t)} dt \geq \int_a^{\infty} \frac{1}{12t^{5/6}} dt = \infty.$$

Hence we have indeed made an improvement by avoiding the condition “ $g'(t) \geq \alpha > 0$ ”.

**3. Example.** Assume that (A2) and (A3) hold. Let  $\alpha \in \mathbf{R}$  and the function

$$p(t) = \begin{cases} t^\alpha & \text{if } t > 0, \\ 0 & \text{if } t = 0. \end{cases}$$

Consider the Klein–Gordon equation (c.f. Example 2.6.3 in [5])

$$x''(t) + p(t)|x(g(t))|\exp(|x(g(t))|^2) = e^{-t} \sin t, \quad t \in [0, \infty) \setminus \Upsilon, \quad (46)$$

$$x(t_k^+) = a_k x(t_k), \quad k \in \mathbf{N}, \quad (47)$$

$$x'(t_k^+) = a_k x'(t_k), \quad k \in \mathbf{N}, \quad (48)$$

where  $a_k$  are positive constants for  $k \in \mathbf{N}$  such that (A7) holds. We can easily check that

$$z(t) = A(0, t) \int_{\frac{3\pi}{2}}^t \int_{\frac{3\pi}{4}}^s \frac{e^{-v} \sin v}{A(0, v)} dv ds, \quad t \geq \frac{3\pi}{2},$$

is a solution of the system

$$z''(t) = e^{-t} \sin t, \quad t \in [0, \infty) \setminus \Upsilon,$$

$$z(t_k^+) = a_k z(t_k), \quad k \in \mathbf{N},$$

$$z'(t_k^+) = a_k z'(t_k), \quad k \in \mathbf{N}.$$

Since

$$z(t) \geq m \int_{\frac{3\pi}{2}}^t \int_{\frac{3\pi}{4}}^s e^{-v} \sin v dv ds \geq m \left( \frac{e^{-t}}{2} \cos t \right)$$

and

$$z(t) \leq M \int_{\frac{3\pi}{2}}^t \int_{\frac{3\pi}{4}}^s e^{-v} \sin v dv ds = M \left( \frac{e^{-t}}{2} \cos t \right)$$

for  $t \geq 3\pi/2$ , we may see that  $z(t)$  is oscillatory and  $\lim_{t \rightarrow \infty} z(t) = 0$ . Before stating the following conclusions, recall that a function  $\varphi$  defined for all sufficiently large  $t$  is oscillatory if  $\varphi$  is neither eventually positive nor eventually negative.

(1) It is easy to check that all hypotheses of Corollary 3 are satisfied. We first note that  $\alpha < -2$  if, and only if,

$$\int_1^{\infty} \int_s^{\infty} \frac{v^\alpha}{A(s, v)} dv ds < \infty.$$

By Corollary 3, we can see that  $\alpha < -2$  if, and only if, the system (46)–(48) has a nonoscillatory solution  $x$  which is bounded.

(2) It is easy to check that all hypotheses of Corollary 2 are satisfied. Assume that  $m \geq 1$  and  $\alpha \geq -1$ . Then

$$\int_1^{\infty} \frac{p(t)}{A(0, t)} dt = \int_1^{\infty} \frac{t^\alpha}{A(0, t)} dt \geq \int_1^{\infty} \frac{t^\alpha}{M} dt = \infty.$$

Since

$$\sum_{i=1}^{\infty} \left( \prod_{1 \leq t_j < t_i} \frac{1}{a_j} \right) \int_{t_{i-1}}^{t_i} p(t) dt = \int_0^{\infty} \frac{t^\alpha}{A(0, t)} dt = \infty.$$

By Theorem 1 in [4], then every solution of system

$$x''(t) + p(t) |x(g(t))| \exp(|x(g(t))|^2) = 0, \quad t \in [0, \infty) \setminus \Upsilon, \quad (49)$$

$$x(t_k^+) = a_k x(t_k), \quad k \in \mathbf{N}, \quad (50)$$

$$x'(t_k^+) = a_k x'(t_k), \quad k \in \mathbf{N}, \quad (51)$$

is oscillatory. By Corollary 3, we can further see that every solution of system (46)–(48) is oscillatory.

(3) Assume that  $g'(t) > 0$  for  $t \geq 0$ ,  $a_k \geq 1$  for  $k \in \mathbf{N}$ . Since

$$\int_{\varepsilon}^{\infty} \frac{e^{-\mu}}{\mu} d\mu \leq \frac{1}{\varepsilon} \int_{\varepsilon}^{\infty} e^{-\mu} d\mu < \infty \quad \text{for any } \varepsilon > 0,$$

by Theorem 4, we see that if  $\alpha \geq -2$ , then every solution of system (46)–(48) is oscillatory.

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