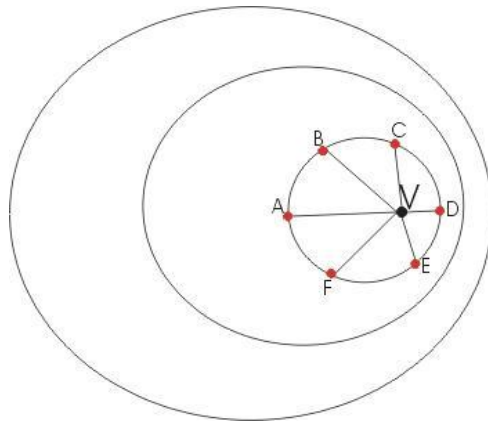


**ОБ ОДНОМ ПОДХОДЕ
К МОДЕЛИРОВАНИЮ ЗАДАЧ
УРОВНЯ ВОДОЗАПАСА И ПАВОДКА
ДЛЯ РАЗЛИЧНЫХ РЕЛЬЕФОВ
МЕСТНОСТИ**

: 1)

; 2)

- [1].
- 1) ;
 - 2) ;
 - 3) A, B, C, D, E, F (60°);
 - 4) (W);
 - 5) ($t \in [0, N\tau]$);
 - 6) $\Delta t = \tau$.
- V (1).



1. A, B, C, D, E, F
 2. F, K
- $i+1-1$
- F
- 2.

... , ...
 ()
 ; $h -$; $Q -$; $\omega -$
 $v = Q/ -$; $J -$;

dl (. . . 1).
 $0 - 0,$ $2 - 2:$

$$h + idl + \frac{p_o}{\rho g} + \frac{\alpha v^2}{2g} = h + dh + \frac{p_o}{\rho g} + \frac{\alpha(v + dv)^2}{2g} + dh \quad (1)$$

$$\frac{dh}{dl} = \frac{i - \frac{Q^2}{\omega^2 C^2 R} + \frac{\alpha Q^2}{g \omega^3} \frac{\partial \omega}{\partial s} \frac{ds}{dl}}{1 - \frac{\alpha Q^2 B}{g \omega^3}} \quad (2)$$

$$\frac{dh}{dl} = i - \frac{Q^2}{\omega^2 C R} \left/ \left(1 - \frac{\alpha Q^2 B}{g \omega^3} \right) \right. \quad (3)$$

(2) (3) :

$$= \frac{\alpha Q^2 B}{g \omega^3} = \frac{\alpha v^2 / g}{\omega / B} = \frac{2\alpha v^2 / 2g}{h} \quad (4)$$

$h = \omega/ -$, (3)

$h = h$ $\alpha = 1$
 $Fr = v^2/gh,$
 $h [2].$

1. $\beta_i = 1, \beta_{i-1} = 0,$ (5)

2. (S_i)

3. \vdots

$$m_i = W \tau_i S_i + (1 - \beta_{i-1}) W \tau_{i-1} S_{i-1}. \quad (5)$$

4. $S(\dots)$

$b -$ (\dots)

$$h(y) = \eta y - \bar{\eta} b, \quad (6)$$

$$h(y) = - \eta y, \quad (7)$$

V $(\alpha \beta \bar{O} \text{ const})$

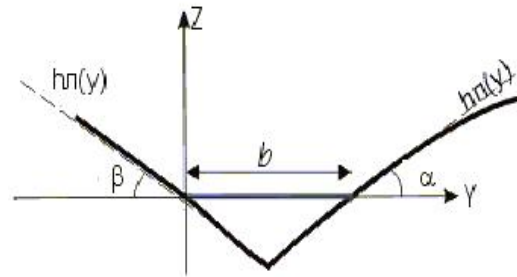
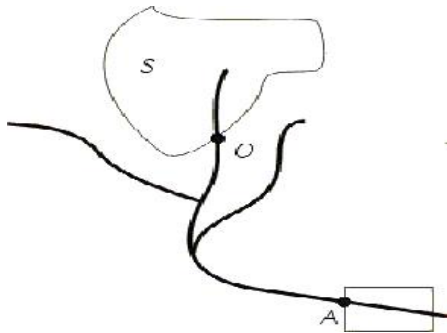
$$\frac{1}{V_A \cdot \rho} \cdot \frac{dM \left(t - \frac{x_A}{V_A} \right)}{dt} = bz + \int_{y(z)}^0 [z - h(y)] dy + \int_b^{y(z)} [z - h(y)] dy. \quad (8)$$

$$(8) \quad y(z) - h(y) = z. \quad (9)$$

$$(9) \quad (7) \quad \eta y = z \Rightarrow y(z) = -z / \eta. \quad (10)$$

$$h(y) = z. \quad (11)$$

$$(11) \quad (6) \quad \eta y - \bar{\eta} b = z \Rightarrow y(z) = b + z / \eta. \quad (12)$$



4.

—
—

S () ;

(8) – (12),

z

(4,).

z

/

1.

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i -

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[2],

() [2],

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—);

(

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2.

() S .

3.

:

$$\sum = \iint_S dx dy \cdot n(x, y), \quad (13)$$

$n(x, y) -$

($n(x, y)$

[2]); $K(j, r) -$

: $n(x, y) = n_{\max} \cdot K(j, r)$,

,

; $K(j, r) = 0.5 K(j, r) + 1, 0 -$

, $1 -$

