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Magnetomechanical Effects in the Elastic Polymer Composites Containing Ferromagnetic Powder Particles

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In the present work, a detailed thermodynamic consideration for the magnetic free energy of the composite material consisting of the ferromagnetic powder particles embedded into a polymer matrix is given. We estimate their magnetostatic interaction energy and its dependence on the microscopic distribution of the magnetization and the magnetic field in the composite material. We also define the hydrostatic component of the mechanical force developed in a composite and the volume change effect caused by the magnetostatic interactions in such composites.

Key words: magnetomechanical effect, magnetostriction, elastic polymer, ferromagnetic powder, composite material.

В даній роботі дається детальна термодинамічна аналіза магнетної вільної енергії композитного матеріалу, що складається з ферромагнетних порошкових частинок, втілених у пружню полімерну матрицю. Ми даємо оцінку їхньої енергії магнетної взаємодії та її залежність від мікроскопічного розподілу намагнетованости та магнетного поля всередині композитного матеріалу. Ми також визначаємо гідростатичну компоненту механічних напружень, що розвиваються у композиті, та ефект зміни об'єму, зумовлений магнетостатичною взаємодією порошкових частинок у таких композитах.

Ключові слова: магнетомеханічний ефект, магнетострикція, пружні полімери, ферромагнетні порошки, композитні матеріали.

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В данной работе даётся детальный термодинамический анализ магнитной свободной энергии композитного материала, который состоит из ферромагнитных порошковых частиц, внедрённых в упругую полимерную матрицу. Мы даём оценку их энергии магнитного взаимодействия и её зависимости от микроскопического распределения намагниченности и магнитного поля внутри композитного материала. Мы также определяем гидростатическую компоненту механических напряжений, которые развиваются в композите, и эффект изменения объёма, обусловленный магнитостатическими взаимодействиями порошковых частиц в таких композитах.

Ключевые слова: магнитомеханический эффект, магнитострикция, упругие полимеры, ферромагнитные порошки, композитные материалы.

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1. INTRODUCTION

In the last years, the study of heterogeneous materials consisting of magnetic micro- and nanoparticles imbedded into a nonmagnetic matrix has been increasing due to its importance for understanding micromagnetic interactions in these systems as well as for possible applications [1, 2]. When the magnetic particles are magnetized and the matrix material is elastic, an elastic magnet is obtained. This material may exhibit elastomagnetic effects [3, 4], and it can be used for sensors and actuators [5, 6]. In order to have optimum performances for the mentioned applications, the material must have a high content of magnetic particles.

During these years, several different materials were tested: magnetoelastic composite with the filling particles made of magnetostrictive, hard or soft ferromagnetic material [7, 8]. Some possible applications in the airplane and car industries as actuators or antifriction components [9], heat-shrinkable elastic ferromagnets with the variable magnetic and conductive properties [10] were discussed. Those papers were dealing with a similar kind of materials and focusing on the theoretical and experimental correlation of the material elasticity with its magnetic behaviour.

In particular, they analysed a composite of particles uniformly dispersed inside the matrix material: a) the particles having an asymmetric shape, preferably with a main anisotropy axis; b) the particles, which were soft ferromagnetic or small permanent magnets; c) the composites having an elastic behaviour, due to the matrix properties, up to a relative deformation. In these conditions, a strong coupling acts between magnetization axis and the main shape anisotropy axis of the particles. Therefore, a change of the magnetizing field along an axis different from the easy magnetization one gives a rotation of the

particles due to the mechanical torque, in order to align the magnetic moments with the applied field [4]. The macroscopic effect of these local rotations can be a deformation of the whole material. The inverse effect [11] consists in the change of magnetization axis due to a deformation of the elastic material. As an example, an elongation of the elastomagnetic material produces a rotation of each particle and a consequent rotation of its magnetic moment because it is strongly coupled with the particles geometry. This also gives a variation of the magnetization component along the elongation axis. In conclusion, the inverse elastomagnetic effect can be used to have a strain sensor detecting deformation by means of the induced magnetization changes at constant temperature and magnetizing field [3, 12, 13].

A general target of the present work is to produce a detailed thermodynamic consideration for the magnetic free energy of the composite material consisting of the ferromagnetic powder particles embedded into a polymer matrix. We estimate their magnetostatic interaction energy and its dependence on the microscopic distribution of the magnetization and the magnetic field in the composite. We also define the hydrostatic component of the mechanical force and the volume change effect caused by the magnetostatic interactions in such composites.

2. MAGNETIC FREE ENERGY, MAGNETIC FORCES, AND STRAIN EFFECT IN POLYMER COMPOSITES CONTAINING FERROMAGNETIC PARTICLES

Generally, the magnetic forces can be produced in any ferromagnetic material when it magnetizes. Everything depends on the fact, if the material is deformable and if the magnetic free energy per unit volume $F^{\text{mag}}(\mathbf{h}, \boldsymbol{\varepsilon})$ is dependent not only on the external magnetic field \mathbf{h} , but also on the strain of the material $\boldsymbol{\varepsilon}$. Here, we have defined the magnetic free energy to be zero at $\mathbf{h} = \mathbf{0}$. So, it represents only a magnetic part of the total free energy of the material $F^{\text{mag}}(\mathbf{h}, \boldsymbol{\varepsilon}) = F(\mathbf{0}, \boldsymbol{\varepsilon}) + F^{\text{mag}}(\mathbf{h}, \boldsymbol{\varepsilon})$. In such a case, both the macroscopic magnetization of the material $\mathbf{m}(\mathbf{h}, \boldsymbol{\varepsilon})$ and the field-induced magnetic forces $\boldsymbol{\sigma}^{\text{mag}}(\mathbf{h}, \boldsymbol{\varepsilon})$ can be represented on the basis of the general thermodynamic relationships as follows:

$$\mathbf{m}^{\text{mag}}(\mathbf{h}, \boldsymbol{\varepsilon}) = -\left(\frac{\partial}{\partial \mathbf{h}} F^{\text{mag}}(\mathbf{h}, \boldsymbol{\varepsilon})\right)_{\boldsymbol{\varepsilon}}, \quad \boldsymbol{\sigma}^{\text{mag}}(\mathbf{h}, \boldsymbol{\varepsilon}) = -\left(\frac{\partial}{\partial \boldsymbol{\varepsilon}} F^{\text{mag}}(\mathbf{h}, \boldsymbol{\varepsilon})\right)_{\mathbf{h}}. \quad (1)$$

In absence of the magnetic field, any deformable material can be strained elastically or unelastically applying the external mechanical load $\boldsymbol{\sigma}$. In that case, the strain response of the material can be represented by its zero-field stress-strain relationship $\boldsymbol{\sigma} = \boldsymbol{\sigma}^0(\boldsymbol{\varepsilon})$. In general case, when both the mechanical forces and the magnetic ones are ap-

plied, they work altogether simultaneously, and a corresponding strain effect can be found from the following force balance equation:

$$\boldsymbol{\sigma} + \boldsymbol{\sigma}^{\text{mag}}(\mathbf{h}, \boldsymbol{\sigma}) = \boldsymbol{\sigma}^0(\boldsymbol{\varepsilon}). \quad (2)$$

So, in two partial cases $\boldsymbol{\sigma} = \mathbf{0}$ and $\mathbf{h} = \mathbf{0}$, we obtain very similar relationships:

$$\boldsymbol{\sigma}^{\text{mag}}(\mathbf{h}, \boldsymbol{\varepsilon}) = \boldsymbol{\sigma}^0(\boldsymbol{\varepsilon}) \text{ and } \boldsymbol{\sigma} = \boldsymbol{\sigma}^0(\boldsymbol{\varepsilon}), \quad (3)$$

where the first one defines implicitly the magnetic-field-induced strain (MFIS) effect in a particular ferromagnetic material, which is generally dependent both on its magnetic properties and also on the mechanical behaviour of the material represented by its zero-field strain–stress relationship $\boldsymbol{\sigma} = \boldsymbol{\sigma}^0(\boldsymbol{\varepsilon})$. For instance, in the ordinary magnetostrictive materials, it is given by a well-known linear and completely reversible Hook's law. In other recently discovered large MFIS systems like ferromagnetic shape-memory NiMnGa alloy, the straining mechanism is not elastic and based on the field-induced twinning occurring in these systems.

3. HYDROSTATIC MAGNETIC FORCES AND VOLUME CHANGE IN POLYMER COMPOSITES CONTAINING FERROMAGNETIC PARTICLES

Here, we will apply the previously discussed idea to understand what the hydrostatic magnetic forces can be developed in systems consisting of the multiple ferromagnetic particles imbedded into some elastically soft polymer matrix and what the volume changes can be expected in similar materials.

For that, we introduce the total magnetic free energy F of such a composite system of a volume V and containing totally the volume V_m of all ferromagnetic particles randomly distributed in the polymer matrix. We also assume that the saturation magnetization M_s of the bulk ferromagnetic material per its unit volume is known and that the saturation magnetization of each particular is the same.

In that case, $F(V, V_m, h)$ can be represented in the following general form:

$$F(V, V_m, h) = VF_m \left(\frac{V_m}{V}, h \right) = VF_m(z, h), \quad (4)$$

where $F_m(z, h)$ is the magnetic free energy per unit volume of the composite, h is the external magnetic field, and $z = V_m/V$ is the volume fraction of the ferromagnetic material in the composite. This gives us

the possibility to define the hydrostatic pressure developed in a magnetic field as follows:

$$P_m(z, h) = \frac{\partial}{\partial V} \left(VF_m \left(\frac{V_m}{V}, h \right) \right) = F_m(z, h) - z \left(\frac{\partial}{\partial z} F_m(z, h) \right)_h. \quad (5)$$

We can also define the magnetization per unit volume of the composite material accordingly:

$$M(z, h) = -\frac{\partial}{\partial h} \left(F_m \left(\frac{V_m}{V}, h \right) \right)_V = -\frac{\partial}{\partial h} (F_m(z, h))_z. \quad (6)$$

4. MAGNETOSTATIC ENERGY IN POLYMER COMPOSITES

Generally, the total magnetic free energy of a composite material F containing N ferromagnetic particles magnetized to its full saturation consists of the Zeeman's and magnetostatic (demagnetizing) energy contributions. It can be represented as follows:

$$F = -\sum_{p=1}^N v_p \left(\mathbf{h} \mathbf{m}_p + \frac{1}{2} \mathbf{h}_p \mathbf{m}_p \right). \quad (7)$$

Here, v_p are the particle volumes, $\mathbf{m}_p = M_s \mathbf{e}_h$ —their local magnetizations all fully magnetized parallel to the external magnetic field \mathbf{h} , and \mathbf{h}_p is the local demagnetizing field averaged over the particle volume.

The local demagnetizing field is produced by the surface magnetic charges induced both at the external surface of the composite material and at the particle interface, where normal magnetization components have jumps. Therefore, it can be written in the following manner:

$$\mathbf{h}_p = -4\pi \mathbf{D} \mathbf{m} - 4\pi \mathbf{D}_p (\mathbf{m}_p - \mathbf{m}), \quad (8)$$

where $\mathbf{m}_p = M_s \mathbf{e}_h$, \mathbf{m} is the macroscopic magnetization of the fully saturated composite material:

$$\mathbf{m} = \frac{1}{V} \sum_{p=1}^N v_p \mathbf{m}_p = z M_s \mathbf{e}_h, \quad V_m = \sum_{p=1}^N v_p. \quad (9)$$

Here, \mathbf{D} , \mathbf{D}_p are the demagnetizing matrices representing both the composite material and the ferromagnetic particle dependent only on their shapes. So, finally, for the magnetic free energy per unit volume of the composite material, we obtain:

$$F_m(z, h) = \frac{1}{2} 4\pi (\bar{D}_p z + (D - \bar{D}_p) z^2) (M_s)^2 - z M_s h. \quad (10)$$

Here, D , \bar{D}_p are the components of the demagnetizing matrices parallel to the external magnetic field applied. It is important that \bar{D}_p is defined as the average demagnetizing factor of the ferromagnetic particle system:

$$\bar{D}_p = \frac{1}{V_m} \sum_{p=1}^N v_p D_p, \quad V_m = \sum_{p=1}^N v_p. \quad (11)$$

In particular, it means that, if all the particles are randomly oriented, then their average demagnetizing factor must be equal $\bar{D}_p = 1/3$ even if all of them are not really the spherical ones. In other words, the ferromagnetic material distribution in the polymer matrix is statistically isotropic in this case.

Using Eqs. (5) and (10), one can also obtain the magnetic pressure:

$$P(z, h) = -\frac{1}{2} 4\pi(D - \bar{D}_p)z^2 M_s^2. \quad (12)$$

The corresponding calculation results are represented in Fig. 1.

As follows from these results, the maximal magnetic force, which is achieved in the completely saturated composite samples with the randomly oriented particles, is strongly dependent on the volume fraction of the ferromagnetic material and the demagnetizing factor of the composite samples. It may have different signs as the demagnetizing

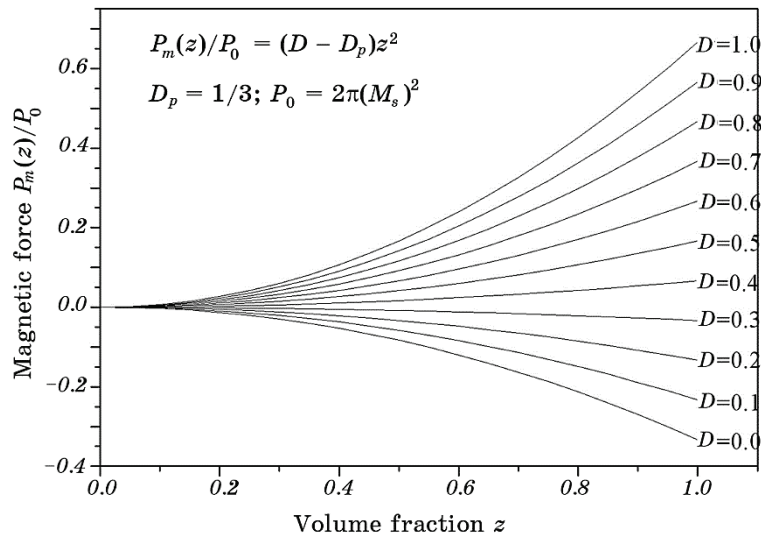


Fig. 1. Dependence of the magnetic pressure developed in a fully saturated composite containing the randomly oriented ferromagnetic particles at the different demagnetizing factors D of the composite samples.

factor changes within the range $0 < D < 1$. In case $D = 0$ (the sample is a long cylinder parallel to the magnetic field), the magnetic force will produce a compression effect. In the other case $D = 1$ (the sample is a thin plate aligned perpendicular to the magnetic field), the magnetic force will cause an extension. A general characteristic scale of the magnetic forces is defined by the material constant $P_0 = 2\pi(M_s)^2$ proportional to the saturation magnetization squared.

5. STRAIN EFFECT PRODUCED BY MAGNETIC FORCES

As follows from Eq. (3), the relative volume change must be proportional to the magnetic force developed in a composite material and reverse proportional to its effective bulk elastic modulus $C(z)$.

$$\frac{\delta V}{V} = \varepsilon_{\text{vol}}(z, h) = K(z)P(z, h), \quad K(z) = (C(z))^{-1}. \quad (13)$$

Here, $K(z)$ is obviously a bulk elastic compressibility of the composite material. As follows from the mechanical testing experiments shown in Fig. 2, the elastic moduli of the polymer composites containing the rigid powder particles are strongly dependent on its volume fraction.

These results indicate that the bulk elastic modulus is sharply goes up as the volume fraction of rigid particles increases so as the compressibility decreases approximately linearly. Therefore, for some practical reasons, we can use a following simple linear model for the

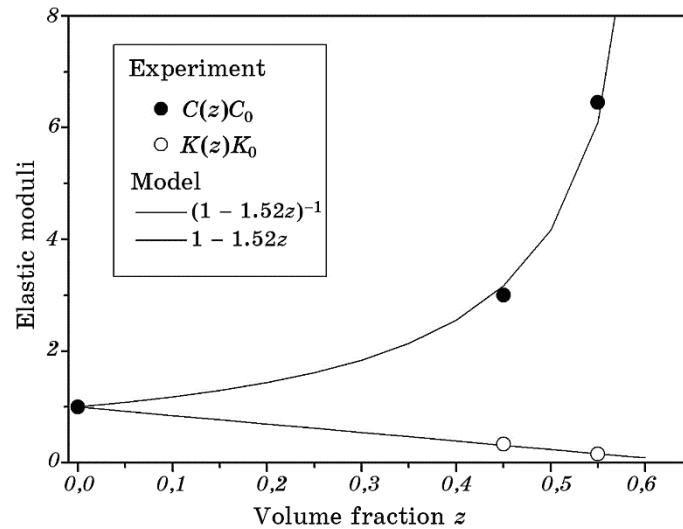


Fig. 2. Fraction dependence of bulk elastic modulus and elastic compressibility.

elastic compressibility:

$$K(z) = K_0(1 - z). \quad (14)$$

It means that only the compressibility of polymer matrix K_0 gives a contribution into $K(z)$ proportional to its volume fraction $(1 - z)$. So, finally, we obtain the field induced volume effect:

$$\varepsilon_{vol}(z, h) = -2\pi K_0 (M_s)^2 (D - \bar{D}_p) z^2 (1 - z). \quad (15)$$

It is strongly dependent on both the sample and ferromagnetic particle shapes represented by the difference between their demagnetizing factors. It is also strongly dependent on the volume fraction of ferromagnetic material. The general scale of the field-induced effects is defined by the material constant proportional to the elastic compressibility of the polymer and squared saturation magnetization of bulk ferromagnetic material. The fraction dependent factor has a maximum at the volume fraction at about $z = 2/3$. These final results are shown in Fig. 3.

6. CONCLUSIONS

The magnetic free energy of the composite material consists of the magnetostatic energy of separate ferromagnetic powder particles, their magnetostatic interaction energy, and the Zeeman's energy. It is strongly dependent on the volume fraction of magnetic powder and the

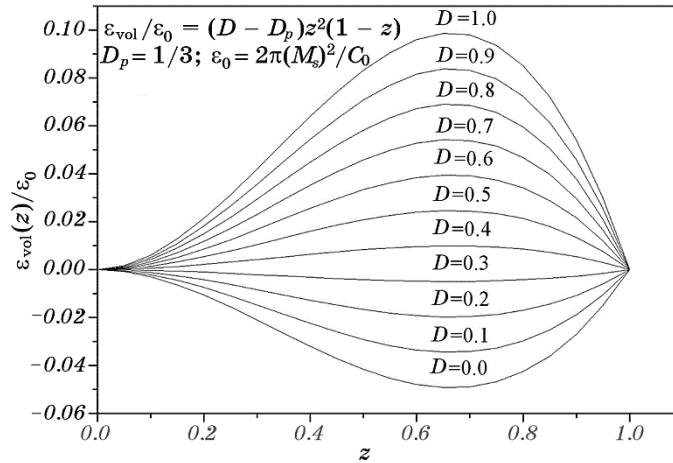


Fig. 3. Elastomagnetic volume change effect and its dependence on the volume fraction of ferromagnetic powder and demagnetizing factor of the composite sample.

magnetic field applied.

Both the macroscopic magnetization and the hydrostatic magnetic forces can be obtained from the magnetic free energy as functions of the volume fraction and the magnetic field applied by using the general differential thermodynamic relationships.

The micromagnetic model of the polymer composite consisting of the ferromagnetic powders and elastically soft polymer matrix developed here has given the expression for the magnetostatic energy and the magnetic forces as functions of the volume fraction, magnetic field and the macroscopic demagnetizing factors of the composite samples. It has given a possibility to estimate the maximal field induced strain effect and its dependence on the volume fraction of the ferromagnetic material.

The experimental study of the elastic moduli of the polymer composites containing the different volume fraction of powder particles has shown its strong dependence on the volume fraction of powder. One can use these results to estimate the fraction dependence of the field induced strain effect, its dependence on the volume fraction of the ferromagnetic material, and its maximal value.

Finally, we have concluded that the field induced volume effect is strongly dependent on the sample and ferromagnetic-particle shapes represented by the difference between their demagnetizing factors. It is also strongly dependent on the volume fraction of ferromagnetic material. The general scale of the field-induced effects is defined by the material constant proportional to the elastic compressibility of the polymer and squared saturation magnetization of bulk ferromagnetic material. The fraction dependent factor has a maximum at the volume fraction at about $z = 2/3$.

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