# Scattering from Sparse Potentials on Graphs 

Ph. Poulin<br>Department of Mathematical Sciences<br>Norwegian University of Science and Technology 7491 Trondheim, Norway<br>E-mail:poulin@math.ntnu.no

Received October 1, 2007
We study the spectral structure of Schrödinger operators $H=\Delta+V$ for random potentials supported on sparse sets. In the past years examples of such operators whose spectra almost surely satisfy the following properties have been exhibited: Anderson localization holds outside spec( $\Delta$ ), while the wave operators $\Omega^{ \pm}(H, \Delta)$ exist inside this last set. We continue this program by presenting sparseness conditions under which $\Omega^{ \pm}(\Delta, H)$ also exist.

Key words: random Schrödinger operators, spectral analysis, scattering theory.

Mathematics Subject Classification 2000: 81Q10, 47B80.

## 1. Introduction

Since its introduction in 1958, there has been considerable interest in the Anderson model [4], which describes potentials that are not completely known, but are affected by a probability distribution. By focusing on almost sure results (and hence by discarding pathological constructions), research on this model has given a new insight into quantum physics. A random potential, $V$, lies on a lattice $\mathbb{Z}^{d}$. It is described by the following operator on $l^{2}\left(\mathbb{Z}^{d}\right)$ :

$$
V=\sum_{N \in \mathbb{Z}^{d}} V(N)\left\langle\delta_{N} \mid \cdot\right\rangle \delta_{N},
$$

where $\delta_{N}(M)$ is the Kronecker delta and $\{V(N)\}_{N \in \mathbb{Z}^{d}}$ is a family of i.i.d. random variables of law $\nu .{ }^{*}$ The spectral structure of the random Hamiltonian

$$
H=\Delta+\lambda V
$$

[^0]has been investigated-where $\lambda$ is a positive number (the so-called disorder) and $\Delta$ is the centered discrete Laplacian. It was proven by L. Pastur that the absolutely continuous, essential, singular continuous and point spectra of $H$ are almost surely constant [20]. Indeed, from the first days Anderson has conjectured that $H$ has the following spectral structure (almost surely): if $\lambda$ is small, $\operatorname{spec}(H)$ is purely absolutely continuous (delocalization) except near its edges, where it is pure point with exponentially decaying eigenfunctions (Anderson localization); on the other hand, if $\lambda$ is large, Anderson localization occurs on the whole $\operatorname{spec}(H)$. While the structure of the a.c. spectrum of $H$ is still not completely understood, the localization part of the above conjecture was proven by M. Aizenman and S. Molchanov [3, 1]. In their works these authors developed a method for estimating the $s^{t h}$-moment of the resolvent's matrix elements
$$
R(M, N, z)=\left\langle\delta_{M} \mid(H-z)^{-1} \delta_{N}\right\rangle
$$
(in absolute value) for suitable $\lambda, s$ and $z$ approaching the real line. This method, which is used in the present paper, is based on the following decoupling lemmas which apply to a large class of probability measures including Gaussian, Cauchy, and uniform distributions $[1-3,5,11,15]:$ *

Proposition 1. Suppose there exists an $s \in(0,1)$ such that

$$
k_{s}=\inf _{\alpha, \beta \in \mathbb{C}} \frac{\int_{\mathbb{R}}|x-\alpha|^{s}|x-\beta|^{-s} \mathrm{~d} \nu(x)}{\int_{\mathbb{R}}|x-\beta|^{-s} \mathrm{~d} \nu(x)}>0 .
$$

Then, for any deterministic function $F(M, N, z)$,

$$
\mathbb{E}|V(M)-F(M, N, z)|^{s}|R(M, N, z)|^{s} \geqslant k_{s} \mathbb{E}|R(M, N, z)|^{s}
$$

Suppose instead there exists an $s \in(0,1)$ such that

$$
K_{s}=\sup _{\beta \in \mathbb{C}} \frac{\int_{\mathbb{R}}|x|^{s}|x-\beta|^{-s} \mathrm{~d} \nu(x)}{\int_{\mathbb{R}}|x-\beta|^{-s} \mathrm{~d} \nu(x)}<\infty .
$$

Then, $\mathbb{E}|V(M)|^{s}|R(M, N, z)|^{s} \leqslant K_{s} \mathbb{E}|R(M, N, z)|^{s}$.
In addition to the Anderson model, several researchers (M. Krishna et al. [13, 14], W. Kirsch et al. [6, 12], S. Molchanov et al. [15-19]) have investigated various sparse models, which describe random potentials lying on a set $\Gamma$ subject to various geometric constraints, having in common that the distance between

[^1]$N \in \Gamma$ and its closest neighbor in $\Gamma$ tends to infinity when $|N| \rightarrow \infty$. In the discrete case the following Hamiltonian on $l^{2}\left(\mathbb{Z}^{d}\right)$ has been investigated,
$$
H=\Delta+V, \quad V=\sum_{n \in \Gamma} V(n)\left\langle\delta_{n} \mid \cdot\right\rangle \delta_{n}
$$
where $\{V(n)\}_{n \in \Gamma}$ is a family of i.i.d. random variables.
Since such a model is not ergodic, Pastur's theorem fails for the singular continuous and point spectra of $H$, but still holds for the essential and continuous spectra. Indeed, the essential spectrum of $H$ has been completely characterized by S. Molchanov and B. Vainberg under appropriate sparseness conditions [17, 19]. In addition, the spectral structure of $H$ (for the above model or its continuous analog) has been clarified in different cases. Families of random Hamiltonians with the following, almost sure properties have been exhibited: the spectrum of $H$ is (possibly dense) pure point outside $\operatorname{spec}(\Delta)$, while the wave operators
$$
\Omega_{E}^{ \pm}(H, \Delta)=\lim _{t \rightarrow \pm \infty} \mathrm{e}^{\mathrm{i} t H} \mathrm{e}^{-\mathrm{i} t \Delta} \mathbf{1}_{E}(\Delta) \quad \text { (strongly) }
$$
exist on the whole $E=\operatorname{spec}(\Delta)$-yielding that $\operatorname{spec}_{\mathrm{ac}}(H)=\operatorname{spec}(\Delta)$.
In order to complete this program we show that under suitable sparseness conditions the above wave operators are almost surely complete, i.e., $\Omega_{E}^{ \pm}(\Delta, H)$ also exist. We conclude this work by exhibiting a family of random operators $H=\Delta+V$ with sparse potentials satisfying almost surely the following properties: $1^{o}$ the spectrum of $H$ is purely absolutely continuous on $\operatorname{spec}(\Delta), 2^{o}$ the wave operators exist and are complete on $\operatorname{spec}(\Delta), 3^{\circ}$ the spectrum of $H$ is (possibly dense) pure point outside $\operatorname{spec}(\Delta)$.

This work, based on a private communication with V. Jakšić, is an application of a completeness criterion found in [9] - a paper of V. Jakšić and Y. Last dedicated to L. Pastur.

Acknowledgements The author is grateful to Vojkan Jakšić for his substantial collaboration, his generous teaching (covering many results used in the present paper), and for having made this invitation possible. The present article is based on the second part of the doctoral dissertation of the author, who wants to acknowledge his thesis' referees for instructive comments.

## 2. Abstract Results

### 2.1. The Model

At a higher level of generality the lattice $\mathbb{Z}^{d}$ is replaced with a countable set $X$ endowed with a graph structure. We assume that this graph consists of finitely many connected components and that the degrees of the vertices are bounded. Let
$\mathrm{d}(M, N)$ be the distance between $M, N \in X$, that is, the length of the shortest path connecting them in $X$ ( $\infty$ if $M$ and $N$ lie on two different components). The usual centered Laplacian is then replaced with the adjacency operator of $X$ : for $\varphi \in l^{2}(X)$,

$$
\Delta \varphi(N)=\sum_{\mathrm{d}(M, N)=1} \varphi(M)
$$

Notice that $\Delta$ is a bounded selfadjoint operator on $l^{2}(X)$. The Euclidean distance is replaced with a weight on the set $X$, that is, a function $\gamma: X \times X \rightarrow[0, \infty)$ satisfying all axioms of metric distance, except that $\gamma(M, N)=0$ does not necessarily imply $M=N$.

For a fixed $\Gamma \subset X$, a family $\{V(n)\}_{n \in \Gamma}$ of i.i.d. random variables is given. Their law, $\nu$, is assumed to be absolutely continuous and to satisfy both hypotheses of Prop. 1 for a fixed $s \in(0,1)$. We study the following random Hamiltonian on $l^{2}(X)$ :

$$
H=\Delta+V, \quad V=\sum_{n \in \Gamma} V(n)\left\langle\delta_{n} \mid \cdot\right\rangle \delta_{n}
$$

Notation. In the sequel the connected components of the graph are denoted by $X_{j}$. For $0 \leqslant R \leqslant \infty$, the $R$-fattening of $\Gamma$ is defined as

$$
\Gamma_{R}=\{\underline{N} \in X ; \mathrm{d}(\underline{N}, \Gamma) \leqslant R\}
$$

while the projection on $l^{2}\left(\Gamma_{R}\right)$ is denoted by $\mathbf{1}_{R}$. For the sake of clarity, we shall use the following fonts: $\underline{n}$ varies in a certain subset of $\Gamma, n$ varies in $\Gamma, \underline{N}$ varies in a certain fattening of $\Gamma$ and $N$ in the whole $X$.

The abbreviation a.e. \& a.s. stands for almost everywhere and almost surely, where the former refers to the Lebesgue measure and the latter to the given probability measure $\mathbb{P}$. Here, the underlying probability space is given by $\Omega=$ $\mathbb{R}^{\left(\mathbb{Z}^{d}\right)}$ equipped with its Borel $\sigma$-algebra and the probability measure $\mathbb{P}=\prod_{\mathbb{Z}^{d}} \nu$.

### 2.2. Preliminaries

Our work is based on the following Jakšić-Last criterion of completeness [9], whose conclusion trivially persists for disconnected graphs:*

Proposition 2. Suppose that the spectrum of $H$ is purely a.c. on a given Borel set $E \subseteq \mathbb{R}$. Suppose also that $\mathbf{1}_{1}$ is $\Delta$-smooth on $E$, that is,**

$$
\sup _{\substack{0<\varepsilon<1 \\ e \in E}}\left\|\mathbf{1}_{1}(\Delta-e-\mathrm{i} \varepsilon)^{-1} \mathbf{1}_{1}\right\|<\infty
$$

[^2]If for all $n \in \Gamma$ and almost all $e \in E$

$$
\sum_{\underline{M} \in \Gamma_{1}}\left|\operatorname{Im}\left\langle\delta_{\underline{M}} \mid(H-e-\mathrm{i} 0)^{-1} \delta_{n}\right\rangle\right|^{2}<\infty
$$

then the wave operators $\Omega_{E}^{ \pm}(\Delta, H)$ exist.
Since in this context the usual wave operators are $\Omega_{E}^{ \pm}(H, \Delta)$, this last criterion asserts their completeness, but without assuming their existence.

In order to prove localization we shall use the following Simon-Wolff theorem [27]. It is easily seen that its conclusion is valid for disconnected graphs with finitely many components, except regarding simplicity of the eigenvalues - which follows from a recent theorem of V. Jakšić and Y. Last [10].

Proposition 3. Let $E \subseteq \mathbb{R}$ be a Borel set. If with probability one

$$
\left\|(H-e-\mathrm{i} 0)^{-1} \delta_{n}\right\|<\infty
$$

for all $n \in \Gamma$ and almost all $e \in E$, then the spectrum of $H$ on $E$ is almost surely pure point with simple eigenvalues.*

Suppose in addition that for almost all $V \in \Omega$, almost all $e \in E$, and all $n \in \Gamma$ there exist constants $K, k>0$ independent of $M \in X$ such that

$$
\left|\left\langle\delta_{n} \mid(H-e-\mathrm{i} 0)^{-1} \delta_{M}\right\rangle\right| \leqslant K \mathrm{e}^{-k \gamma(n, M)}
$$

Then, the eigenfunctions are exponentially bounded in the following sense: for such an eigenfunction $\psi(N)$ and an arbitrarily fixed site $N_{0}$, there exists a coefficient Const (depending on $V, N_{0}$ and the associated eigenvalue) and a universal exponent $k>0$ such that

$$
|\psi(N)| \leqslant \text { Const } \mathrm{e}^{-k \gamma\left(N, N_{0}\right)}
$$

for all $N \in X$.
Given a selfadjoint operator $T$ on $l^{2}(X)$, let $T_{j}$ be its restriction to $l^{2}\left(X_{j}\right)$. The essential support of the a.c. spectrum of $T_{j}$ is given by

$$
\Sigma\left(T_{j}\right)=\left\{e \in \mathbb{R} ; \sum_{N \in X_{j}}\left|\operatorname{Im}\left\langle\delta_{N} \mid\left(T_{j}-e-\mathrm{i} 0\right)^{-1} \delta_{N}\right\rangle\right|>0\right\} \text { a.e. }
$$

Notice that $\Sigma\left(T_{j}\right)$ is defined up to a set of Lebesgue measure zero; however, its equivalence class is almost surely constant (by a variant of Pastur's theorem). We define

$$
\Sigma(T)=\cap_{j} \Sigma\left(T_{j}\right)
$$

The Jakšić-Last theorem [8] asserts:

[^3]Proposition 4. Let $E \subseteq \mathbb{R}$ be a Borel set. If with probability one $E \subset \Sigma(H)$ (in the sense that $E \backslash \Sigma(H)$ has Lebesgue measure zero), then the spectrum of $H$ on $E$ is purely a.c., almost surely.

### 2.3. Main Results

As mentioned in the previous section we shall determine the spectral structure of $H$ on a given interval $[a, b]$ by using the Jakšić-Last and the Simon-Wolff criteria (depending on the location of $[a, b]$ ). In both cases the matrix elements of the resolvent of $H$ have to be estimated. This will be done in one step, using the Aizenman-Molchanov method.*

Consider the following quantity,

$$
\tau(M, N)=\sup _{z \in \mathcal{S}}\left|\left\langle\delta_{M} \mid(\Delta-z)^{-1} \delta_{N}\right\rangle\right|
$$

where $M, N \in X$ and $\mathcal{S}=\{a \leqslant \operatorname{Re} z \leqslant b, 0<\operatorname{Im} z<1\}$. In concrete models $\tau(M, N)$ decays when $M$ and $N$ become distant. This motivates our choice in the present abstract setting to make sparseness assumptions on $\tau(M, N)$ :

Assumption A. For all $\varepsilon>0$ there exists a finite set $\mathcal{F} \subseteq \Gamma$ such that $\sum_{n \in \Gamma \backslash\{\underline{m}\}} \tau(n, \underline{m})^{s}<\varepsilon$ for all $\underline{m} \in \Gamma \backslash \mathcal{F}$.

Given an $R \in[0, \infty]$,
Assumption B. $\sup _{n \in \Gamma} \sum_{\underline{M} \in \Gamma_{R}} \tau(n, \underline{M})^{s}<\infty$.
Let $\mathfrak{I}=\inf _{n \in \Gamma, z \in \mathcal{S}}\left|\left\langle\delta_{n} \mid(\Delta-z)^{-1} \delta_{n}\right\rangle\right|$. We also assume
Assumption C. $\quad \mathfrak{I}>0$.
Our chief lemma is:
Lemma 1. Suppose $0 \leqslant R \leqslant \infty$. Under Assumptions $A, B$ and $C$, for all $n \in \Gamma$,

$$
\left\|\mathbf{1}_{R}(H-e-\mathrm{i} 0)^{-1} \delta_{n}\right\|<\infty \text { a.e. } \mathcal{G} \text { a.s. }
$$

on $[a, b] \times \Omega$.

[^4]We deduce the following result inside $\operatorname{spec}(\Delta)$ :
Theorem 1. Suppose $A, C$, and $\sup _{\underline{N} \in \Gamma_{1}} \sum_{\underline{M} \in \Gamma_{1}} \tau(\underline{N}, \underline{M})^{s}<\infty$ for an interval $[a, b] \subset \Sigma(\Delta)$. If $\Omega_{[a, b]}^{ \pm}(H, \Delta)$ exist a.s., then the spectrum of $H$ on $[a, b]$ is purely a.c. and the wave operators are complete there, almost surely.

In order to derive Anderson localization outside $\operatorname{spec}(\Delta)$ we make the following assumptions on the weight:

Assumption D. For any $k>0, \sup _{N \in X} \sum_{M \in X} \mathrm{e}^{-k \gamma(N, M)}<\infty$.
As sumption E. For each $L>0$ there exists a finite set $\mathcal{E} \subseteq \Gamma$ such that for all $\underline{m} \in \Gamma \backslash \mathcal{E}, \inf _{n \in \Gamma \backslash\{\underline{m}\}} \gamma(n, \underline{m}) \geqslant L$.

Given an $R \in[0, \infty]$,
Assumption F. There exist $D, \beta$ such that $\tau(n, \underline{M})^{s} \leqslant D \mathrm{e}^{-\beta \gamma(n, \underline{M})}$ for all $n \in \Gamma$ and $\underline{M} \in \Gamma_{R}$.

Our main lemma is:
Lemma 2. Suppose $0 \leqslant R \leqslant \infty$. Under Assumptions $C, D$, $E$, and $F$, there exists a universal constant $k>0$ such that the following holds a.e. 6 a.s. on $[a, b] \times \Omega:$ for all $n \in \Gamma$ there exists a $K>0$ such that

$$
\left|\left\langle\delta_{n} \mid(H-e-\mathrm{i} 0)^{-1} \delta_{\underline{M}}\right\rangle\right| \leqslant K \mathrm{e}^{-k \gamma(n, \underline{M})}
$$

for all $\underline{M} \in \Gamma_{R}$.
From Lemmas 1 and 2 we deduce:
Theorem 2. Suppose $C, D$, and E. Suppose in addition $F$ holds with $R=\infty$. Then, the spectrum of $H$ on $[a, b]$ is almost surely pure point with simple eigenvalues and exponentially bounded eigenfunctions (in the sense of Prop. 3).

### 2.4. Proof of the First Lemma

In this section Assumption A is used in the following form: there exists a finite set $\mathcal{F} \subset \Gamma$ such that

$$
\begin{equation*}
\sup _{\underline{m} \in \Gamma \backslash \mathcal{F}} \sum_{n \in \Gamma \backslash\{\underline{m}\}} \tau(n, \underline{m})^{s}<\frac{\mathfrak{I}^{s} k_{s}}{2 K_{s}} \tag{1}
\end{equation*}
$$

We also assume B for an arbitrary $R \in[0, \infty]$, and C.

Let $\widehat{H}=\Delta+\sum_{\underline{n} \in \Gamma \backslash \mathcal{F}} V(\underline{n})\left\langle\delta_{\underline{n}} \mid \cdot\right\rangle \delta_{\underline{n_{n}}}$. We use the abbreviations

$$
\begin{aligned}
R_{0}(N, M, z) & =\left\langle\delta_{N} \mid(\Delta-z)^{-1} \delta_{M}\right\rangle, \\
R(N, M, z) & =\left\langle\delta_{N} \mid(H-z)^{-1} \delta_{M}\right\rangle, \\
\widehat{R}(N, M, z) & =\left\langle\delta_{N} \mid(\widehat{H}-z)^{-1} \delta_{M}\right\rangle,
\end{aligned}
$$

where $M, N \in X$ and $z \in \mathcal{S}$. Since the spectral measure of $\delta_{M}$ and $\delta_{N}$ with respect to $H$ is real-valued [9], $R(N, M, z)=R(M, N, z)$ for any $z \in \mathcal{S}$; similar relations hold for $R_{0}$ and $\widehat{R}$.

In the sequel we use the Aizenman-Molchanov decoupling lemmas (Prop. 1) in conjunction with the resolvent identity; this latter implies

$$
\begin{equation*}
\widehat{R}(N, M, z)=R_{0}(N, M, z)-\sum_{\underline{p} \in \Gamma \backslash \mathcal{F}} R_{0}(N, \underline{p}, z) V(\underline{p}) \widehat{R}(\underline{p}, M, z) \tag{2}
\end{equation*}
$$

for all $M, N \in X$. As a first instance, with the convention that $\underline{p}$ varies in $\Gamma \backslash \mathcal{F}$,
Lemma 3. For all $\underline{n}, \underline{m} \in \Gamma \backslash \mathcal{F}$ and $z \in \mathcal{S}$,

$$
\mathbb{E}|\widehat{R}(\underline{n}, \underline{m}, z)|^{s} \leqslant \frac{1}{k_{s} \mathfrak{I}^{s}} \tau(\underline{n}, \underline{m})^{s}+\frac{K_{s}}{k_{s} \mathfrak{I}^{s}} \sum_{\underline{p} \neq \underline{n}} \tau(\underline{n}, \underline{p})^{s} \mathbb{E}|\widehat{R}(\underline{p}, \underline{m}, z)|^{s} .
$$

Proof. By the equation (2),

$$
\widehat{R}(\underline{n}, \underline{m}, z)\left(1+R_{0}(\underline{n}, \underline{n}, z) V(\underline{n})\right)=R_{0}(\underline{n}, \underline{m}, z)-\sum_{\underline{p} \neq \underline{n}} R_{0}(\underline{n}, \underline{p}, z) V(\underline{p}) \widehat{R}(\underline{p}, \underline{m}, z) .
$$

Using the triangle inequality for $|\cdot|^{s}$, taking the expectation, and then applying the decoupling lemmas give $k_{s}\left|R_{0}(\underline{n}, \underline{n}, z)\right|^{s} \mathbb{E}|\widehat{R}(\underline{n}, \underline{m}, z)|^{s} \leqslant\left|R_{0}(\underline{n}, \underline{m}, z)\right|^{s}+$ $K_{s} \sum_{\underline{p} \neq \underline{n}}\left|R_{0}(\underline{n}, \underline{p}, z)\right|^{s} \mathbb{E}|\widehat{R}(\underline{p}, \underline{m}, z)|^{s}$, from which the result follows.

Let us fix $\underline{m} \in \Gamma \backslash \mathcal{F}$ and $z \in \mathcal{S}, \underline{n} \in \Gamma \backslash \mathcal{F}$ being thought as the only variable. We define the following vectors on $l^{\infty}(\Gamma \backslash \mathcal{F})$ :

$$
\begin{aligned}
X(\underline{n}) & =\mathbb{E}|\widehat{R}(\underline{n}, \underline{m}, z)|^{s}, \\
B(\underline{n}) & =\frac{1}{k_{s} \Im^{s}} \tau(\underline{n}, \underline{m})^{s} .
\end{aligned}
$$

They are well defined, since $\|X\|_{\infty} \leqslant|\operatorname{Im} z|^{-s}$ and $\|B\|_{\infty}<\infty$, the latter by Assumption B (which also ensures $\|B\|_{1}<\infty$ ). Let us define the operator

$$
(A \psi)(\underline{n})=\frac{K_{s}}{k_{s} \mathfrak{I}^{s}} \sum_{\underline{p} \neq \underline{n}} \tau(\underline{n}, \underline{p})^{s} \psi(\underline{p})
$$

which acts on both $l^{\infty}(\Gamma \backslash \mathcal{F})$ and $l^{1}(\Gamma \backslash \mathcal{F})$. By the equation (1),

$$
\begin{equation*}
\|A\|_{\infty}=\|A\|_{1}=\frac{K_{s}}{k_{s} \mathfrak{I}^{s}} \sup _{\underline{n}} \sum_{\underline{p} \neq \underline{n}} \tau(\underline{n}, \underline{p})^{s}<\frac{1}{2} \tag{3}
\end{equation*}
$$

In addition, the previous lemma gives $(1-A) X \leqslant B$ (pointwise).
Lemma 4. $\sup _{z \in \mathcal{S}} \sup _{\underline{m} \in \Gamma \backslash \mathcal{F}} \sum_{\underline{n} \in \Gamma \backslash \mathcal{F}} \mathbb{E}|\widehat{R}(\underline{n}, \underline{m}, z)|^{s}<\infty$.
Proof. The relation (3) implies that $(1-A)^{-1}=\sum_{j=0}^{\infty} A^{j}$ is well-defined and satisfies $\left\|(1-A)^{-1}\right\|_{1} \leqslant 2$. Observe that, since all matrix elements of $A$ are positive, those of $(1-A)^{-1}$ are also positive, i.e., $(1-A)^{-1}$ preserves pointwise positivity. Therefore, by the previous lemma

$$
\begin{equation*}
X \leqslant(1-A)^{-1} B \quad \text { (pointwise) } \tag{4}
\end{equation*}
$$

so $\|X\|_{1} \leqslant 2\|B\|_{1}$. In other words, $\sum_{\underline{n}} \mathbb{E}|\widehat{R}(\underline{n}, \underline{m}, z)|^{s} \leqslant \frac{2}{k_{s} \widetilde{\mathcal{T}}^{s}} \sum_{\underline{n}} \tau(\underline{n}, \underline{m})^{s}$. Since $\underline{m}$ and $z$ are arbitrary, Assumption B yields the result.

Lemma 5. For all $M, N \in X$ and $z \in \mathcal{S}$,

$$
\mathbb{E}|\widehat{R}(N, M, z)|^{s} \leqslant \tau(N, M)^{s}+K_{s} \sum_{\underline{p} \in \Gamma \backslash \mathcal{F}} \tau(N, \underline{p})^{s} \mathbb{E}|\widehat{R}(\underline{p}, M, z)|^{s}
$$

Proof. The result is obtained by applying the triangle inequality for $|\cdot|^{s}$ to (2), taking the expectation, and then using the decoupling lemma.

Lemma 6. $\sup _{z \in \mathcal{S}} \sup _{n \in \Gamma} \sum_{\underline{M} \in \Gamma_{R}} \mathbb{E}|\widehat{R}(n, \underline{M}, z)|^{s}<\infty$.
Proof. Assumption B and Lemma 4 imply that $C=\sup _{n \in \Gamma} \sum_{\underline{M} \in \Gamma_{R}} \tau(n, \underline{M})^{s}$ and $D=\sup _{z \in \mathcal{S}} \sup _{\underline{m} \in \Gamma \backslash \mathcal{F}} \sum_{\underline{n} \in \Gamma \backslash \mathcal{F}} \mathbb{E}|\widehat{R}(\underline{n}, \underline{m}, z)|^{s}$ are finite. By the previous lemma, for all $\underline{N} \in \Gamma_{R}, \underline{m} \in \Gamma \backslash \mathcal{F}$ and $z \in \mathcal{S}$,

$$
\mathbb{E}|\widehat{R}(\underline{N}, \underline{m}, z)|^{s} \leqslant \tau(\underline{N}, \underline{m})^{s}+K_{s} \sum_{\underline{p} \in \Gamma \backslash \mathcal{F}} \tau(\underline{N}, \underline{p})^{s} \mathbb{E}|\widehat{R}(\underline{p}, \underline{m}, z)|^{s}
$$

and hence $\sup _{z \in \mathcal{S}} \sup _{\underline{m} \in \Gamma \backslash \mathcal{F}} \sum_{\underline{N} \in \Gamma_{R}} \mathbb{E} \mid\left(\left.\widehat{R}(\underline{N}, \underline{m}, z)\right|^{s} \leqslant C+K_{s} C D\right.$. By the same lemma, for all $n \in \Gamma, \underline{M} \in \Gamma_{R}$ and $z \in \mathcal{S}$

$$
\mathbb{E}|\widehat{R}(n, \underline{M}, z)|^{s} \leqslant \tau(n, \underline{M})^{s}+K_{s} \sum_{\underline{p} \in \Gamma \backslash \mathcal{F}} \tau(n, \underline{p})^{s} \mathbb{E}|\widehat{R}(\underline{p}, \underline{M}, z)|^{s}
$$

and hence $\sum_{\underline{M} \in \Gamma_{R}} \mathbb{E}|\widehat{R}(n, \underline{M}, z)|^{s} \leqslant C+K_{s} C\left(C+K_{s} C D\right)$ uniformly in $n \in \Gamma$ and $z \in \mathcal{S}$, as desired.

We want to deduce information about $\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)$ for $n \in \Gamma, \underline{M} \in \Gamma_{R}$ and $e \in[a, b]$; this last limit exists a.e. \& a.s. on $[a, b] \times \Omega$ (by classical Analysis and Fubini's theorem).

Lemma 7. For all $n \in \Gamma, \sum_{\underline{M} \in \Gamma_{R}}|\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)|^{2}<\infty$ a.e. छ a.s. on $[a, b] \times \Omega$.

Proof. For a fixed $n \in \Gamma$,

$$
\int_{a}^{b} \mathbb{E} \sum_{\underline{M} \in \Gamma_{R}}|\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)|^{s} \mathrm{~d} e \leqslant(b-a) \operatorname{ess} \sup _{a<e<b} \sum_{\underline{M} \in \Gamma_{R}} \mathbb{E}|\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)|^{s},
$$

where ess sup denotes the essential supremum w.r.t. the Lebesgue measure. Hence, by Fatou's lemma

$$
\int_{a}^{b} \mathbb{E} \sum_{\underline{M} \in \Gamma_{R}}|\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)|^{s} \mathrm{~d} e \leqslant(b-a) \sup _{z \in \mathcal{S}} \sum_{\underline{M} \in \Gamma_{R}} \mathbb{E}|\widehat{R}(n, \underline{M}, z)|^{s} .
$$

The result follows from the previous lemma and the triangle inequality for $|\cdot|^{\frac{s}{2}}$.
We are now ready to prove Lemma 1 . Let $n \in \Gamma$. By the resolvent identity, for all $\underline{M} \in \Gamma_{R}$

$$
R(n, \underline{M}, e+\mathrm{i} 0)=\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)-\sum_{p \in \mathcal{F}} V(p) \widehat{R}(p, \underline{M}, e+\mathrm{i} 0) R(n, p, e+\mathrm{i} 0)
$$

a.e. \& a.s. on $[a, b] \times \Omega$. Consequently, $\sum_{\underline{M} \in \Gamma_{R}}|R(n, \underline{M}, e+\mathrm{i} 0)|^{2}$ is less than or equal to $A\left(\sum_{\underline{M} \in \Gamma_{R}}|\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)|^{2}+\bar{M}(e) \sum_{p \in \mathcal{F}}|V(p)|^{2}|R(n, p, e+\mathrm{i} 0)|^{2}\right)$ a.e. \& a.s., where $M(e)=\max _{p \in \mathcal{F}} \sum_{\underline{M} \in \Gamma_{R}}|\widehat{R}(p, \underline{M}, e+\mathrm{i} 0)|^{2}$ and $A$ is the number of elements of $\mathcal{F}$ plus one. Then the finiteness of $\mathcal{F}$ and the previous lemma complete the proof.

### 2.5. Proof of the Second Lemma

Now we assume C, D, E, and F. Assumption D extends by induction:
Lemma 8. For any $k$ and $\alpha$ such that $0<\alpha<k$ there exists a $C_{k, \alpha}>0$ satisfying

$$
\begin{equation*}
\sum_{P_{1}, \ldots, P_{l} \in X} \mathrm{e}^{-k\left(\gamma\left(N, P_{1}\right)+\gamma\left(P_{1}, P_{2}\right)+\cdots+\gamma\left(P_{l}, M\right)\right)} \leqslant C_{k, \alpha}^{l} \mathrm{e}^{-\alpha \gamma(N, M)} \tag{5}
\end{equation*}
$$

for every $N, M \in X$ and $l \in \mathbb{N}$.

Proof. There exists an $s \in(0,1)$ such that $\alpha=s k$. By Assumption D, $B_{k^{\prime}}=\sup _{N \in X} \sum_{M \in X} \mathrm{e}^{-k^{\prime} \gamma(N, M)}<\infty$ for any $k^{\prime}>0$. Let us show that $C_{k, \alpha}=$ $B_{t k}$ then satisfies the desired property, where $t=1-s$.

The triangle inequality for $\gamma$ implies that the left-hand side in (5) is bounded above by $\sum_{P_{1}, \ldots, P_{l}} \mathrm{e}^{-t k\left(\gamma\left(N, P_{1}\right)+\cdots+\gamma\left(P_{l}, M\right)\right)} \mathrm{e}^{-\alpha \gamma(N, M)}$ for any fixed $l \geqslant 0$. It is thus sufficient to show $\sum_{P_{1}, \ldots, P_{l}} \mathrm{e}^{-t k\left(\gamma\left(N, P_{1}\right)+\cdots+\gamma\left(P_{l}, M\right)\right)} \leqslant B_{t k}^{l}$ for any $l \geqslant 0$.

The result is trivial if $l=0$. Suppose it holds for $l-1$. Then,

$$
\begin{aligned}
\sum_{P_{1}, \ldots, P_{l}} \mathrm{e}^{-t k\left(\gamma\left(N, P_{1}\right)+\cdots+\gamma\left(P_{l}, M\right)\right)} & =\sum_{P_{1}} \mathrm{e}^{-t k \gamma\left(N, P_{1}\right)} \sum_{P_{2}, \ldots, P_{l}} \mathrm{e}^{-t k\left(\gamma\left(P_{1}, P_{2}\right)+\cdots+\gamma\left(P_{l}, M\right)\right)} \\
& \leqslant B_{t k} B_{t k}^{l-1}=B_{t k}^{l}
\end{aligned}
$$

as desired.
As a final preliminary remark,
Lemma 9. All assumptions of the previous section are satisfied.
Proof. Assumption B follows from Assumptions D and F. Assumption A is satisfied, since for any finite $\mathcal{E} \subset \Gamma$ and $\underline{n} \in \Gamma \backslash \mathcal{E}$,

$$
\sum_{m \in \Gamma \backslash\{\underline{n}\}} \tau(m, \underline{n})^{s} \leqslant\left(D \sup _{p \in \Gamma} \sum_{q \in \Gamma \backslash\{p\}} \mathrm{e}^{-\frac{\beta}{2} \gamma(p, q)}\right) \sup _{m \in \Gamma \backslash\{\underline{n}\}} \mathrm{e}^{-\frac{\beta}{2} \gamma(\underline{n}, m)}
$$

where the right-hand side goes to zero as $\mathcal{E} \uparrow X$ (by Assumptions D and E ). Finally, Assumption C is satisfied by fiat.

We are thus free to use the results and computations of the previous section. Recall that $\mathcal{F} \subset \Gamma$ is a finite set chosen in such a way that the relation (1) holds. From now, by enlarging $\mathcal{F}$ if necessary, we also require*

$$
\begin{equation*}
\mathrm{e}^{-\frac{\beta}{2} \widehat{d}}<\frac{\mathfrak{I}^{s} k_{s}}{K_{s} C_{\frac{\beta}{2}, \frac{\beta}{3}} D} \tag{6}
\end{equation*}
$$

where $\widehat{d}=\inf _{\underline{m} \in \Gamma \backslash \mathcal{F}} \inf _{\underline{n} \in(\Gamma \backslash \mathcal{F}) \backslash\{\underline{m}\}} \gamma(\underline{n}, \underline{m})$; this may be done by Assumption E.
Let $\underline{m} \in \Gamma \backslash \mathcal{F}$ and $z \underline{\mathcal{S}}$ be fixed, $\underline{n} \in \Gamma \backslash \mathcal{F}$ being thought as the only variable. Then, with the notation of the previous section the inequation (4) applies, namely $X \leqslant(1-A)^{-1} B$ (pointwise). Consequently,

Lemma 10. $X \leqslant \operatorname{Const}(1-A)^{-1} \delta_{\underline{m}}$ (pointwise).

[^5]Proof. Observe that $\left(A \delta_{\underline{m}}\right)(\underline{n})=K_{s} B(\underline{n})-\frac{K_{s}}{k_{s^{s}}} \tau(\underline{m}, \underline{m})^{s} \delta_{\underline{m}}(\underline{n})$, and hence $B=\frac{1}{K_{s}} A \delta_{\underline{m}}+\frac{1}{k_{s} s^{s}} \tau(\underline{m}, \underline{m})^{s} \delta_{\underline{m}}$. By the inequation (4),

$$
X \leqslant\left(\frac{1}{K_{s}}+\frac{\tau(\underline{m}, \underline{m})^{s}}{k_{s} \mathfrak{I}^{s}}\right)(1-A)^{-1} \delta_{\underline{m}} \quad \text { (pointwise). }
$$

The result follows, with Const $=\frac{1}{K_{s}}+\frac{1}{k_{s} \mathcal{J}^{s}} \sup _{\underline{p} \in \Gamma \backslash \mathcal{F}} \tau(\underline{p}, \underline{p})^{s}$ (which is finite by Assumption B).

Lemma 11. There exist universal constants Const and $k$ such that

$$
\mathbb{E}|\widehat{R}(\underline{n}, \underline{m}, z)|^{s} \leqslant \text { Const } \mathrm{e}^{-k \gamma(\underline{n}, \underline{m})}
$$

for all $\underline{n}, \underline{m} \in \Gamma \backslash \mathcal{F}$ and $z \in \mathcal{S}$.
Proof. By the previous lemma,

$$
\begin{equation*}
\mathbb{E}|\widehat{R}(\underline{n}, \underline{m}, z)|^{s} \leqslant \text { Const } \sum_{j=0}^{\infty}\left\langle\delta_{\underline{n}} \mid A^{j} \delta_{\underline{m}}\right\rangle . \tag{7}
\end{equation*}
$$

Moreover,

$$
A^{j}(\underline{n}, \underline{m})=\left(\frac{K_{s}}{k_{s} \mathfrak{\Im}^{s}}\right)^{j} \sum_{\underline{p}_{1}, \cdots, \underline{p}_{j-1} \in \Gamma \backslash \mathcal{F}} \mathbf{1}_{\underline{n} \neq \underline{p}_{1}} \tau\left(\underline{n}, \underline{p}_{1}\right)^{s} \ldots \underline{1}_{\underline{p}_{j-1} \neq \underline{\underline{m}}} \tau(\underline{p} j-1, \underline{m})^{s},
$$

where $\mathbf{1}_{\underline{p} \neq \underline{q}}=1-\delta_{\underline{p}}(\underline{q})$. By Assumption $\mathrm{F}, \mathbf{1}_{\underline{p} \neq \underline{q}} \tau(\underline{p}, \underline{q})^{s} \leqslant D \mathrm{e}^{-\frac{\beta \hat{d}}{2}} \mathrm{e}^{-\frac{\beta}{2} \gamma(\underline{p}, \underline{q})}$ for $\underline{p}, \underline{q} \in \Gamma \backslash \overline{\mathcal{F}}$. Hence, Lem. 8 implies

$$
\begin{aligned}
A^{j}(\underline{n}, \underline{m}) & \leqslant\left(\frac{K_{s} D \mathrm{e}^{-\frac{\beta \hat{d}}{2}}}{k_{s} \mathfrak{\Im}^{s}}\right)^{j} \sum_{\underline{p}_{1}, \cdots, \underline{p}_{j-1}} \mathrm{e}^{-\frac{\beta}{2} \gamma\left(\underline{n}, \underline{p}_{1}\right)} \ldots \mathrm{e}^{-\frac{\beta}{2} \gamma\left(\underline{p}_{j-1}, \underline{m}\right)} \\
& \leqslant \frac{1}{C_{\frac{\beta}{2}, \frac{\beta}{3}}}\left(\frac{K_{s} C_{\frac{\beta}{2}, \frac{\beta}{3}} D \mathrm{e}^{-\frac{\beta \hat{d}}{2}}}{k_{s} \mathfrak{\Im}^{s}}\right)^{j} \mathrm{e}^{-\frac{\beta}{3} \gamma(\underline{n}, \underline{m})} .
\end{aligned}
$$

By choice of $\mathcal{F}$ the equation (6) holds, so there exist constants Const and $k$ such that $\sum_{j=0}^{\infty} A^{j}(\underline{n}, \underline{m}) \leqslant$ Const $\mathrm{e}^{-k \gamma(\underline{n}, \underline{m})}$. The equation (7) then completes the proof.

Lemma 12. There exist constants Const and $k$ such that for each $n \in \Gamma$, $\underline{M} \in \Gamma_{R}$ and $z \in \mathcal{S}$,

$$
\mathbb{E}|\widehat{R}(n, \underline{M}, z)|^{s} \leqslant \text { Const } \mathrm{e}^{-k \gamma(n, \underline{M})} .
$$

Proof. For $\underline{N} \in \Gamma_{R}$ and $\underline{m} \in \Gamma \backslash \mathcal{F}$, Lem. 5, Assumption F , and the previous lemma yield

$$
\begin{aligned}
\mathbb{E}|\widehat{R}(\underline{N}, \underline{m}, z)|^{s} & \leqslant \tau(\underline{N}, \underline{m})^{s}+K_{s} \sum_{\underline{p} \in \Gamma \backslash \mathcal{F}} \tau(\underline{N}, \underline{p})^{s} \mathbb{E}|\widehat{R}(\underline{p}, \underline{m}, z)|^{s} \\
& \leqslant \text { Const } \mathrm{e}^{-k \gamma(\underline{N}, \underline{m})}+K_{s} \sum_{\underline{p} \in \Gamma \backslash \mathcal{F}} \text { Const } \mathrm{e}^{-k \gamma(\underline{N}, \underline{p})} \mathrm{e}^{-k \gamma(\underline{p}, \underline{m})}
\end{aligned}
$$

where Const and $k$ denote generic constants. It follows from Lem. 8 that $\mathbb{E}|\widehat{R}(\underline{N}, \underline{m}, z)|^{s} \leqslant$ Const $\mathrm{e}^{-k \gamma(\underline{N}, \underline{m})}$. Using this last inequation and Lem. 5 again, a similar computation then gives the result.

Lemma 13. For all $n \in \Gamma$ and almost all $(e, V) \in[a, b] \times \Omega$ there exist constants, Const and $k$, the latter being universal, satisfying

$$
|\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)| \leqslant \text { Const } \mathrm{e}^{-k \gamma(n, \underline{M})}
$$

for all $\underline{M} \in \Gamma_{R}$.
Proof. Let $n \in \Gamma$ be fixed and $\underline{M} \in \Gamma_{R}$. Recall that $\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)$ exists for almost all $(e, V) \in[a, b] \times \Omega$. Thus, the previous result and Fatou's lemma yield

$$
\mathbb{E} \int_{a}^{b}|\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)|^{s} \mathrm{~d} e \leqslant \text { Const } \mathrm{e}^{-k \gamma(n, \underline{M})}
$$

Let $A_{\underline{M}}=\left\{(e, V) \in[a, b] \times \Omega ;|\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)|>\mathrm{e}^{-\frac{k}{2 s} \gamma(n, \underline{M})}\right\}$, where $k$ refers to the previous inequality. Then, denoting by $d$ the Lebesgue measure,

$$
\begin{aligned}
\sum_{\underline{M} \in \Gamma_{R}}(\mathrm{~d} \times \mathrm{d} \mathbb{P})\left(A_{\underline{M}}\right) & \leqslant \sum_{\underline{M} \in \Gamma_{R}} \mathbb{E} \int_{a}^{b} \mathrm{e}^{\frac{k}{2} \gamma(n, \underline{M})}|\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)|^{s} \mathrm{~d} e \\
& \leqslant \text { Const } \sum_{\underline{M} \in \Gamma_{R}} \mathrm{e}^{-\frac{k}{2} \gamma(n, \underline{M})}
\end{aligned}
$$

which is finite by Assumption D. Hence, by Cantelli's lemma there exists a finite $\mathcal{E} \subseteq \Gamma_{R}$ such that for all $\underline{M} \in \Gamma_{R} \backslash \mathcal{E}$

$$
|\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)| \leqslant \mathrm{e}^{-\frac{k}{2 s} \gamma(n, \underline{M})} \quad \text { a.e. \& a.s. }
$$

where $n \in \Gamma$ is arbitrarily fixed. Since $\mathcal{E}$ is finite, the result follows.

Lemma 14. Let $\mathcal{E} \subset \Gamma$ be finite. For a given $n \in \Gamma$ and almost all $(e, V) \in$ $[a, b] \times \Omega$ there exist constants, $K$ and $k$, the latter being universal, satisfying

$$
|\widehat{R}(q, \underline{M}, e+\mathrm{i} 0)| \leqslant K \mathrm{e}^{-k \gamma(n, \underline{M})}
$$

for all $\underline{M} \in \Gamma_{R}$ and $q \in \mathcal{E}$.
P r o of. Since $\mathcal{E}$ is finite, the last lemma ensures for almost all $(e, V)$ the existence of constants satisfying $|\widehat{R}(q, \underline{M}, e+\mathrm{i} 0)| \leqslant$ Const $\mathrm{e}^{-k \gamma(q, \underline{M})}$ for all $\underline{M} \in \Gamma_{R}$ and $q \in \mathcal{E}$. Since $\mathrm{e}^{-k \gamma(q, \underline{M})} \leqslant \mathrm{e}^{k \gamma(n, q)} \mathrm{e}^{-k \gamma(n, \underline{M})}$, the result follows, with $K=$ Const $\sup _{q \in \mathcal{E}} \mathrm{e}^{k \gamma(n, q)}$.

We are now ready to prove Lem. 2. By the resolvent identity, for all $n \in \Gamma$, $\underline{M} \in \Gamma_{R}$, and almost all $(e, V) \in[a, b] \times \Omega$

$$
R(n, \underline{M}, e+\mathrm{i} 0)=\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)-\sum_{p \in \mathcal{F}} R(n, p, e+\mathrm{i} 0) V(p) \widehat{R}(p, \underline{M}, e+\mathrm{i} 0) .
$$

In particular, there exists a constant, namely, $L=\sup _{p \in \mathcal{F}}|R(n, p, e+\mathrm{i} 0) V(p)|$, which depends on $n, e$, and $V$, but not on $\underline{M}$, satisfying

$$
|R(n, \underline{M}, e+\mathrm{i} 0)| \leqslant|\widehat{R}(n, \underline{M}, e+\mathrm{i} 0)|+L \sum_{p \in \mathcal{F}}|\widehat{R}(p, \underline{M}, e+\mathrm{i} 0)| .
$$

The result follows from the previous lemma applied to $\mathcal{E}=\mathcal{F} \cup\{n\}$.

### 2.6. Proofs of the Theorems

Lemma 15. Let $0 \leqslant R \leqslant \infty$. If

$$
\sup _{\underline{N} \in \Gamma_{R}} \sum_{\underline{M} \in \Gamma_{R}} \tau(\underline{N}, \underline{M})^{s}<\infty
$$

then $\mathbf{1}_{R}$ is $\Delta$-smooth on $[a, b]$.
Proof. The triangle inequality for $|\cdot|^{s}$ and the hypothesis yield

$$
\sup _{\underline{N} \in \Gamma_{R}} \sum_{\underline{M} \in \Gamma_{R}}\left|\left\langle\delta_{\underline{N}} \mid(\Delta-z)^{-1} \delta_{\underline{M}}\right\rangle\right| \leqslant \text { Const }
$$

uniformly in $z \in \mathcal{S}$. Interpreting $\mathbf{1}_{R}(\Delta-z)^{-1} \mathbf{1}_{R}$ as an operator on $l^{2}\left(\Gamma_{R}\right)$, its $l^{1}$ and $l^{\infty}$ norms are given by the above expression. Therefore, Schur's interpolation theorem implies $\sup _{z \in \mathcal{S}}\left\|\mathbf{1}_{R}(\Delta-z)^{-1} \mathbf{1}_{R}\right\|<\infty$, as desired.

Proofofthefirst theorem. Since $[a, b] \subset \Sigma(\Delta)$, we also have $[a, b] \subset \Sigma(H)$ for all $V$ such that $\Omega_{[a, b]}^{ \pm}(H, \Delta)$ exist, i.e., almost surely. Hence, by Prop. 4 the spectrum of $H$ is purely a.c. on $[a, b]$. Moreover, the previous lemma (with $R=1$ ) and the assumption of the theorem imply that $\mathbf{1}_{1}$ is $\Delta$-smooth. Lemma 1 (with $R=1$ ) and Prop. 2 thus complete the proof.

Proof of the secondtheorem. Lemma 9 and the assumption of the theorem imply Lems. 1 and 2 (both with $R=\infty$ ). The result then follows from Prop. 3.

## 3. Models on $\mathbb{Z}^{d}$

We now turn our attention to the case where $X=\mathbb{Z}^{d}(d \geqslant 2)$, and the graph distance, $\mathrm{d}(M, N)$, is translational invariant. The graph $\left(\mathbb{Z}^{d}, \mathrm{~d}\right)$ is then determined by $\mathcal{V}=\left\{N \in \mathbb{Z}^{d} ; \mathrm{d}(N, 0)=1\right\}$. We set $\gamma(M, N)=|N-M|$.

Recall that the Fourier transform of $\psi \in l^{2}\left(\mathbb{Z}^{d}\right)$ is defined as

$$
\widehat{\psi}(x)=(\mathcal{F} \psi)(x)=(2 \pi)^{-\frac{d}{2}} \sum_{N \in \mathbb{Z}^{d}} \mathrm{e}^{\mathrm{i} N \cdot x} \psi(N)
$$

where $x \in \mathbb{T}^{d}$. The symbol of $\Delta$ is $\widehat{\Delta}=\mathcal{F} \Delta \mathcal{F}^{-1}$. Thus, given a $\mathcal{V} \subset \mathbb{Z}^{d}$, the symbol of the Laplacian associated with $\mathcal{V}$ is the multiplication by

$$
\Phi(x)=\sum_{V \in \mathcal{V}} \mathrm{e}^{\mathrm{i} V \cdot x}=\sum_{V \in \mathcal{V}} \cos (V \cdot x) .
$$

It follows from a change of variables that the spectrum of $\Delta$ is purely a.c. and equal to $[\min \Phi, \# \mathcal{V}]$, where $\# \mathcal{V}$ denotes the cardinality of $\mathcal{V}$.

The Green function of $\Delta$ is defined as $G(M, N, z)=\left\langle\delta_{M} \mid(\Delta-z)^{-1} \delta_{N}\right\rangle$ for $M, N \in \mathbb{Z}^{d}$ and $z \in \mathbb{C}_{+}$. Since ( $\mathbb{Z}^{d}, \mathrm{~d}$ ) is translational invariant, $G(M, N, z)=$ $G(0, N-M, z)$; this last is abbreviated by $G(N-M, z)$. Hence, for any $N \in \mathbb{Z}^{d}$ and $z \in \mathbb{C}_{+}$,

$$
\begin{align*}
G(N, z) & =\left\langle\widehat{\delta_{0}}(x) \mid(\widehat{\Delta}-z)^{-1} \widehat{\delta_{N}}(x)\right\rangle_{2} \\
& =(2 \pi)^{-d} \int_{\mathbb{T}^{d}} \frac{\mathrm{e}^{\mathrm{i} N \cdot x}}{\Phi(x)-z} \mathrm{~d} x . \tag{8}
\end{align*}
$$

Recall that our sparseness assumptions are formulated in terms of

$$
\tau(M, N)=\sup _{z \in \mathcal{S}}|G(N-M, z)|,
$$

where $[a, b]$ is a given interval and $\mathcal{S}=\{a \leqslant \operatorname{Re} z \leqslant b, 0<\operatorname{Im} z<1\}$. Hence the decay of $G(N, z)$ when $N \rightarrow \infty$ has to be a priori known. It is clear that $G(N, z)$
decays exponentially when $[a, b]$ is outside the spectrum of $\Delta$. Moreover, the case where $[a, b] \subset \operatorname{spec}(\Delta)$ has been studied in $[24,23]$ using material from [26, 28, 29]:

Proposition 5. Given a real-valued, analytic and periodic function $\Phi(x)$ on $\mathbb{T}^{d}$, let $\Gamma(e)=\left\{x \in \mathbb{T}^{d} ; \Phi(x)=e\right\}$ and let $G(N, z)$ be defined by (8). Assume, for $\left(a^{\prime}, b^{\prime}\right) \subset \operatorname{Ran} \Phi$ and $\mathcal{S}^{\prime}=\bigcup_{e \in\left(a^{\prime}, b^{\prime}\right)} \Gamma(e)$ :

- $\nabla \Phi(x) \neq 0$ for all $x \in \mathcal{S}^{\prime}$;
- for all $e \in\left(a^{\prime}, b^{\prime}\right), \Gamma(e)$ admits at least $\kappa$ nonvanishing principal curvatures at any point, where $\kappa \geqslant 1$ is a fixed integer.

Then, for $N=|N| \omega$ and $[a, b] \subset\left(a^{\prime}, b^{\prime}\right), \lim _{z \rightarrow e, z \in \mathbb{C}_{+}} G(N, z)$ exists* and is $O\left(|N|^{-\frac{\kappa}{2}}\right)$ uniformly in $(e, \omega) \in[a, b] \times \mathrm{S}^{d-1}$. More generally,

$$
G(N, z)=O\left(|N|^{-\frac{\kappa}{2}} \log |N|\right)
$$

uniformly in $(z, \omega) \in \overline{\mathcal{S}} \times \mathrm{S}^{d-1}$, where $\mathcal{S}=\{e+\mathrm{i} y ; a \leqslant e \leqslant b, 0<y<1\}$.
For example, in the case of the centered Laplacian, which is specified by

$$
\mathcal{V}=\{( \pm 1,0, \ldots, 0),(0, \pm 1, \ldots, 0), \ldots,(0,0, \ldots, \pm 1)\}
$$

and whose spectrum is equal to $[-2 d, 2 d], \Gamma(e)$ defines a regular surface for $e \notin\{-2 d,-2 d+4, \ldots, 2 d-4,2 d\}$, exempt of planarity if in addition $e \neq 0$. Hence, letting $E=\{-2 d,-2 d+4, \ldots, 2 d-4,2 d\} \cup\{0\}, G(N, e+\mathrm{i} 0)=O\left(|N|^{-\frac{1}{2}}\right)$ uniformly on compact subsets of $[-2 d, 2 d] \backslash E$. As an alternative, in order to avoid convexity problems, S. Molchanov and B. Vainberg [17] have suggested to base the discretization of the Laplacian on the diagonal neighbors

$$
\mathcal{V}=\left\{\left(v^{(1)}, \ldots, v^{(d)}\right) ; v^{(j)} \in\{1,-1\} \text { for } j=1, \ldots, d\right\}
$$

The resulting graph consists of $2^{d-1}$ connected components, and the spectrum of its Laplacian is equal to $\left[-2^{d}, 2^{d}\right]$. Remarkably, $\Gamma(e)$ defines a regular, strictly convex surface for $e \notin\left\{-2^{d}, 0,2^{d}\right\}$, as shown in [22]; hence, with $E=\left\{-2^{d}, 0,2^{d}\right\}$, $G(N, e+\mathrm{i} 0)=O\left(|N|^{-\frac{d-1}{2}}\right)$ uniformly on compact subsets of $[-2 d, 2 d] \backslash E$.

Let us translate our abstract results to the present concrete models using the previous proposition. Assumption A and the strengthened version of B assumed in Th. 1 easily reduce to the following sparseness assumption:

Assumption G. There exists an $\epsilon>0$ such that $\sum_{m \in \Gamma \backslash\{n\}} \mid n-$ $\left.m\right|^{-\frac{\kappa s}{2}+\epsilon}<\infty$ for all $n \in \Gamma$, and

$$
\lim _{\substack{|n| \rightarrow \infty \\ n \in \Gamma}} \sum_{m \in \Gamma \backslash\{n\}}|n-m|^{-\frac{\kappa s}{2}+\epsilon}=0
$$

[^6]First consider the case where $[a, b] \subset\left(a^{\prime}, b^{\prime}\right) \subset \operatorname{spec}(\Delta)$ for a given $\left(a^{\prime}, b^{\prime}\right)$ satisfying the hypotheses of the previous proposition. Since $\left(\mathbb{Z}^{d}, d\right)$ is translational invariant,

$$
\mathfrak{I}=\inf _{z \in \mathcal{S}}\left|\left\langle\delta_{0} \mid(\Delta-z)^{-1} \delta_{0}\right\rangle\right|=\inf _{z \in \mathcal{S}}|G(0, z)| .
$$

Moreover, by Th. 6.1 in [24]

$$
\begin{equation*}
\lim _{\substack{z \rightarrow e \\ z \in \mathbb{C}_{+}}} \operatorname{Im} G(0, z)=\pi \int_{\Gamma(e)}\left\|\nabla_{x} \Phi(x)\right\|^{-1} \mathrm{ds}(x)>0 \tag{9}
\end{equation*}
$$

Since in addition $\operatorname{Im} G(0, z)>0$ on $\mathcal{S}$, the above implies C .
Let $\Delta_{j}=P_{j} \Delta P_{j}$, where $P_{j}$ denotes the projection onto $l^{2}\left(X_{j}\right)$. Observe that for any $z \notin \mathbb{R}$

$$
\left\langle\delta_{N} \mid\left(\Delta_{j}-z\right)^{-1} \delta_{N}\right\rangle= \begin{cases}G(0, z) & \text { if } N \in X_{j} \\ 0 & \text { otherwise }\end{cases}
$$

Hence, the equation (9) implies $[a, b] \subset \Sigma(\Delta)$.
Consider now the case where $[a, b]$ is at a positive distance of $\operatorname{spec}(\Delta)$. Then, $\mathfrak{I}$ is clearly positive, i.e., C holds. Assumption D is satisfied for $\gamma(M, N)=|M-N|$. Moreover, Assumption F holds, since $\sup _{z \in \mathcal{S}}|G(N, z)|$ is exponentially decaying. Finally, Assumption E yields our sparseness condition in this case, namely

$$
\text { A ss umption H. } \lim _{\substack{|n| \rightarrow \infty \\ n \in \Gamma}} \inf _{m \in \Gamma \backslash\{n\}}|n-m|=\infty \text {. }
$$

Let $\Theta$ be a reunion of intervals $\left(a^{\prime}, b^{\prime}\right)$ like above. We have proven:
Theorem 3. Suppose $\Gamma$ satisfies $G$. If the wave operators $\Omega_{\Theta}^{ \pm}(H, \Delta)$ exist a.e., then they are complete (and the spectrum of $H$ is purely a.c.) on $\Theta$, almost surely. Suppose instead $\Gamma$ satisfies the weaker assumption $H$. Then, the spectrum of $H$ outside $\operatorname{spec}(\Delta)$ is almost surely pure point with simple eigenvalues and exponentially decaying eigenfunctions.

Remarks.

1. In particular, the previous theorem holds for the standard Laplacian (with $\kappa=1$ ) and the Molchanov-Vainberg Laplacian (with $\kappa=d-1$ ) on $\Theta=$ $\operatorname{spec}(\Delta) \backslash E$, where in both cases $E$ is a finite, deterministic set (described after Prop. 5). By Proposition 4 (for instance), such an $E$ does not contain eigenvalues of $H$, almost surely. In both cases completeness (a.s.) of the wave operators on the whole $\operatorname{spec}(\Delta)$ follows.
2. Additional conditions may be imposed on the geometry of $\Gamma$ in order to assure the existence of the wave operators, including additional sparseness conditions [19].
3. As mentioned in the introduction, by Pastur's theorem the essential spectrum of $H$ is almost surely equal to a deterministic set, which was characterized by S. Molchanov and B. Vainberg [17, 19].* Using their result, one may construct examples in which $\operatorname{spec}_{\text {ess }}(H)=\mathbb{R}$. This is the case for instance when the random potential at each site has a Cauchy or a normal distribution. Then, the spectrum of $H$ is dense pure point in $\mathbb{R} \backslash \operatorname{spec}(\Delta)$.
4. Our study includes another approach, based on Fredholm analytic theory and valid for bounded, deterministic potentials [23]. Under suitable sparseness conditions both existence and completeness of the wave operators are derived on $\operatorname{spec}(\Delta)$ minus a set of Lebesgue measure zero - which disappears in the random frame.

Example. Consider $H=\Delta+V$, where $\Delta$ is the standard (or the MolchanovVainberg) Laplacian. Suppose $\{V(n)\}_{n \in \Gamma}$ is a family of i.i.d. random variables lying on $\Gamma=\left\{\left(j^{4}, 0, \ldots, 0\right) \in \mathbb{Z}^{d} ; j \in \mathbb{Z}\right\}$, whose common distribution is Cauchy (alternatively, normal). Then, $\Gamma$ is sparse in the sense of Th. 3 (with $s$ sufficiently close to 1 ). Moreover, since $\Gamma$ is included in the hyperplane $\mathbb{Z}^{d-1} \subset \mathbb{Z}^{d}$, the existence of $\Omega^{ \pm}(H, \Delta)$ follows from a deterministic result of V. Jakšić and Y. Last [7]..* Hence, by Th. 3 (and the first remark following it), $\operatorname{spec}(H)$ is purely a.c. on $\operatorname{spec}(\Delta)$ and the wave operators are complete there (almost surely). Moreover, by the same theorem (and the third remark following it), the spectrum of $H$ on $\mathbb{R} \backslash \operatorname{spec}(\Delta)$ is dense pure point with simple eigenvalues and exponentially decaying eigenfunctions, almost surely.

## References

[1] M. Aizenman, Localization at Weak Disorder: Some Elementary Bounds. - Rev. Math. Phys. 6 (1994), 1163-1182.
[2] M. Aizenman and G.M. Graf, Localization Bounds for an Electron Gas. - J. Phys. A: Math. Gen. 31 (1998), 6783-6806.

[^7][3] M. Aizenman and S. Molchanov, Localization at Large Disorder and at Extreme Energies: an Elementary Derivation. - Comm. Math. Phys. 157 (1993), 245-278.
[4] P.W. Anderson, Absence of Diffusion in Certain Random Lattices. - Phys. Rev. 109 (1958), 1492-1505.
[5] G.M. Graf, Anderson Localization and the Space-Time Characteristic of Continuum States. - J. Stat. Phys. 75 (1994), 337-346.
[6] D. Hundertmark and W.Kirsch, Spectral Theory of Sparse Potentials. - In: Stochastic Processes, Physics and Geometry: New Interplays, I. - CMS Conf. Proc. 28 (2000), 213-238.
[7] V. Jakšić and Y. Last, Corrugated Surfaces and A.C. Spectrum. - Rev. Math. Phys. 12 (2000), 1465-1503.
[8] V. Jakšić and Y. Last, Spectral Structure of Anderson Type Hamiltonians. - Invent. Math. 141 (2000), 561-577.
[9] V. Jakšić and Y. Last, Scattering from Subspace Potentials for Schrödinger Operators on Graphs. - Markov Proc. and Rel. Fields 9 (2003), 661-674.
[10] V. Jakšić and Y. Last, Simplicity of Singular Spectrum in Anderson Type Hamiltonians. - Duke Math. J. 133 (2006), 185-204.
[11] V. Jakšić and S. Molchanov, Localization of Surface Spectra. - Comm. Math. Phys. 208 (1999), 153-172.
[12] W. Kirsch, Scattering Theory for Sparse Random Potentials. - Random Oper. and Stoch. Eqs. 10 (2002), 329-334.
[13] M. Krishna, Absolutely Continuous Spectrum for Sparse Potentials. - Proc. Indian Acad. Sci. (Math. Sci.) 103 (1993), 333-339.
[14] M. Krishna and J. Obermeit, Localization and Mobility Edge for Sparsely Random Potentials. - IMSc Preprint (1998), arXiv:math-ph/9805015v2.
[15] S. Molchanov, Lectures on Random Media. - In: Lect. Prob. Theory. - Lect. Notes Math. 1581 (1994), 242-411.
[16] S. Molchanov, Multiscattering on Sparse Bumps. - In: Advances in Differential Equations and Mathematical Physics. - Cont. Math. 217 (1998), 157-182.
[17] S. Molchanov and B. Vainberg, Scattering on the System of the Sparse Bumps: Multidimensional Case. - Appl. Anal. 71 (1999), 167-185.
[18] S. Molchanov and B. Vainberg, Multiscattering by Sparse Scatterers. - In: Mathematical and Numerical Aspects of Wave Propagation. - SIAM (2000), 518-522.
[19] S. Molchanov and B. Vainberg, Spectrum of Multidimensional Schrödinger Operators with Sparse Potentials. - Anal. and Comp. Meth. Scattering and Appl. Math. 417 (2000), 231-254.
[20] L. Pastur and A. Figotin, Spectra of Random and Almost-Periodic Operators. Springer-Verlag, Berlin, 1992.
[21] D. Pearson, Singular Continuous Measures in Scattering Theory. - Comm. Math. Phys. 60 (1978), 13-36.
[22] P. Poulin, The Molchanov-Vainberg Laplacian. - Proc. Amer. Math. Soc. 135 (2007), 77-85.
[23] P. Poulin, Random Schrödinger Operators of Anderson Type with Generalized Laplacians and Sparse Potentials. McGill Univ. Ph.D. Thesis, Montréal, 2006.
[24] P. Poulin, Green's Functions of Generalized Laplacians. - In: Probability and Mathematical Physics: a Volume in Honor of Stanislas Molchanov. - CRM Proc. and Lect. Notes 42 (2007), 417-452.
[25] M. Reed and B. Simon, Methods of Modern Mathematical Physics, IV. Analysis of Operators. Acad. Press, New York, 1978.
[26] W. Shaban and B. Vainberg, Radiation Conditions for the Difference Schrödinger Operators. - Appl. Anal. 80 (2002), 525-556.
[27] B. Simon and T. Wolff, Singular Continuous Spectrum under Rank One Perturbations and Localization for Random Hamiltonians. - Comm. Pure and Appl. Math. 39 (1986), 75-90.
[28] E. Stein, Harmonic Analysis: Real-Variable Methods, Orthogonality, and Oscillatory Integrals. Princeton Univ. Press, Princeton, 1993.
[29] B. Vainberg, Asymptotic Methods in Equations of Mathematical Physics. Gordon \& Breach Sci. Publ., New York, 1989.


[^0]:    ${ }^{*}$ Explicitly, the probability space is given by $\Omega=\mathbb{R}^{\left(\mathbb{Z}^{d}\right)}$ equipped with its Borel $\sigma$-algebra and the probability measure $\mathbb{P}=\prod_{\mathbb{Z}^{d}} \nu$. The random variable $V(N)$ then maps an element of $\Omega$ to its $N$-th coordinate.

[^1]:    ${ }^{*}$ In the sequel we use parentheses with $\mathbb{E}$ in the same way as with $\sum$. For instance, $\mathbb{E} X^{s}=$ $\mathbb{E}\left(X^{s}\right), \operatorname{not}(\mathbb{E} X)^{s}$.

[^2]:    ${ }^{*}$ This last observation is deduced from elementary properties of the projections, $P_{j}$, onto $l^{2}\left(X_{j}\right)$, namely: $P_{j} P_{k}=0$ if $j \neq k ; \sum P_{j}$ is the identity; $P_{j} \mathbf{1}_{R}=\mathbf{1}_{R} P_{j}$ for any $j$ and $R$; $f(T) P_{j}=f\left(T P_{j}\right)=P_{j} f(T) P_{j}$ for any bounded Borel function $f$ and $T \in\{\Delta, V, H\}$.
    ${ }^{* *}$ See [25].

[^3]:    ${ }^{*}$ Recall that the spectrum of $H$ on $E$ is defined as $\operatorname{spec}\left(H \chi_{E}(H)\right)$, where $\chi_{E}$ is the characteristic function of $E$; it is not equal to $\operatorname{spec}(H) \cap E$ in general. Moreover, the above conclusion includes the trivial case where $H$ has no spectrum on $E$.

[^4]:    * Compared with the original Aizenman-Molchanov argument complications from two sources arise: since we play with sparseness instead of the disorder, in order to control the norm of a certain operator we remove a finite number of sites and then put them back using the resolvent identity repeatedly; moreover, deletion of these sites never prevents a remaining site to be close to itself, so the diagonal elements have to be treated differently.

[^5]:    ${ }^{*}$ Here, $\beta, D$, and $C_{\frac{\beta}{2}, \frac{\beta}{3}}$ refer to Assumption F and Lem. 8 .

[^6]:    *Without constraints on the approach.

[^7]:    ${ }^{*}$ S. Molchanov and B. Vainberg considered the random operator $H=\Delta+V$, where $\Delta$ is the standard Laplacian. However, their proof may easily be adapted in order to include Laplacians coming from translational invariant graphs on $\mathbb{Z}^{d}$; in particular, the spectrum of $\Delta$ does not have to be centered.
    ** V. Jakšić and Y. Last considered the half-space model (in which the Laplacian does not come from a translational invariant graph) with a random potential at the boundary; however, their argument may be slightly modified in order to include the above situation.

